

Statistical Mechanics
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Lecture - 21
Classical Probability Density, Ergodicity and Microcanonical Ensemble

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So, we determined the dynamical equation for the Probability Density and we said that this is going to be $i \text{ del naught}$; this is the Liouville operator. And the solution to this equation is e to the power minus $L \text{ hat } N \text{ times } t \text{ rho of } X \text{ N comma } 0$.

We also saw that if we set the left hand side to 0, so that $\text{rho of } X \text{ N comma } t$ goes to just as a function of the phase space variables. This would essentially imply that, $\text{rho of } X \text{ N}$ must

depend only on the energy, where your energy, total energy is given by the Hamiltonian which is a function of X^N .

Now, we have been saying that in the phase space, which this inequality let us say. So, when you allow all energies greater than equal to 0 less than equal to E ; then E defines a surface and you have a volume contained within this surface, right. And we said that, in this when we develop this picture of probability density, we classical probability density; we said that imagine that this phase space is now filled with continuum fluid of state points.

This fluid is made up of state points and this flow is essentially governed by the Hamiltonian dynamics. And the fluid of continuum fluid of state points that you are visualizing that we are imagining is essentially an incompressible fluid. But how do we see that this is an incompressible fluid? So, the probability flow within this volume is as is similar or is exactly the same as a probability as a flow of an incompressible fluid.

In an incompressible fluid, the volume element does not change, right. So, which means that, let us say if I look at the volume element d of X^N at a time t ; I have a Jacobian that connects it to the volume element d of X^N at t_0 , right. So, if you imagine two times snapshots one at t_0 , the other one at t and then if you consider a volume element in the phase space, which has denoted by t_0 ; then this volume element will go to a the volume element $d X^N$ at the time t .

So, the question and the relation between these two volume elements are given by this, where J is the Jacobian, which takes you from t_0 to t . So, J of t comma t_0 ; I am sure you have learned Jacobians is $p^N t_0 q^N$, sorry this has to be. So, note that ok; if you let us take one step backward and we want to. So, the volume element over here is d of $p^N t_0 d$ of $q^N t_0$ and the volume element over here is d of $p^N t d$ of $q^N t$, correct.

So, essentially there is a transformation that is involved over here; which means that $p^N t_0$ goes to well; we will not say d , we will say $p^N t_0$ goes to p^N of t and q^N of t_0 goes to q^N of t , right. Once, so this is a transformation and therefore, I can write down the transform the Jacobian for this; this is going to be.

And similarly you will have q^N of t del p^N t_0 del q^N t of del q^N t_0 ; it is exactly the same thing that we have defined earlier when we did thermodynamics if you recall. So, this is the, Jacobian is the determinant of this matrix.

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$d\vec{x}_t^N = J(t, t_0) d\vec{x}_{t_0}^N$

$$J(t, t_0) = \begin{vmatrix} \frac{\partial \vec{p}_t^N}{\partial \vec{p}_{t_0}^N} & \frac{\partial \vec{p}_t^N}{\partial \vec{q}_{t_0}^N} \\ \frac{\partial \vec{q}_t^N}{\partial \vec{p}_{t_0}^N} & \frac{\partial \vec{q}_t^N}{\partial \vec{q}_{t_0}^N} \end{vmatrix}$$

$$\vec{p}_t^N = \vec{p}_{t_0}^N + \dot{\vec{p}}_{t_0}^N \Delta t + \mathcal{O}(\Delta t^2)$$

$$\vec{q}_t^N = \vec{q}_{t_0}^N + \dot{\vec{q}}_{t_0}^N \Delta t + \mathcal{O}(\Delta t^2)$$

$$\frac{\partial \vec{p}_t^N}{\partial \vec{p}_{t_0}^N} = 1 + \frac{\partial \dot{\vec{p}}_{t_0}^N}{\partial \vec{p}_{t_0}^N} \Delta t + \mathcal{O}(\Delta t^2)$$




But let us write down the equation for p^N t plus right and q^N of t is q^N of t_0 plus q dot of N t_0 delta t plus of course, you have higher order terms which is delta t square over here, right. Now, let us look at this derivative now, right. If I look at this derivative, then del p^N t del of p^N t_0 is 1 plus del p dot N t_0 del p^N t_0 times delta t plus order delta t square.

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$$\frac{\partial \bar{p}_t^N}{\partial \bar{p}_{t_0}^N} = 1 + \frac{\partial \dot{\bar{p}}_t^N}{\partial \bar{p}_{t_0}^N} \Delta t + \mathcal{O}(\Delta t^2)$$

$$\frac{\partial \bar{q}_t^N}{\partial \bar{q}_{t_0}^N} = \frac{\partial \dot{\bar{q}}_t^N}{\partial \bar{q}_{t_0}^N} \Delta t + \mathcal{O}(\Delta t^2)$$

$$\frac{\partial \bar{q}_t^N}{\partial \bar{p}_{t_0}^N} = 1 + \frac{\partial \dot{\bar{q}}_t^N}{\partial \bar{p}_{t_0}^N} \Delta t + \mathcal{O}(\Delta t^2)$$

$$J(t, t_0) = \begin{pmatrix} 1 + \frac{\partial \dot{\bar{p}}_t^N}{\partial \bar{p}_{t_0}^N} \Delta t & \frac{\partial \dot{\bar{q}}_t^N}{\partial \bar{p}_{t_0}^N} \Delta t \\ \frac{\partial \dot{\bar{q}}_t^N}{\partial \bar{p}_{t_0}^N} \Delta t & 1 + \frac{\partial \dot{\bar{q}}_t^N}{\partial \bar{q}_{t_0}^N} \Delta t \end{pmatrix}$$



Similarly, \bar{p}_t^N is $\frac{\partial \dot{\bar{p}}_t^N}{\partial \bar{p}_{t_0}^N} \Delta t$ plus higher order terms, right. One can do it for the \bar{q}_t^N also. So, $\frac{\partial \bar{q}_t^N}{\partial \bar{q}_{t_0}^N}$ is going to be $1 + \frac{\partial \dot{\bar{q}}_t^N}{\partial \bar{q}_{t_0}^N} \Delta t$. So, there is no dot here, so one has to be careful; Δt plus order Δt^2 term. So, once we have this and therefore, one can also write down the corresponding term for $\frac{\partial \bar{q}_t^N}{\partial \bar{p}_{t_0}^N}$, right.

So, if I now using this form of the Jacobian using the Hamilton's equation of motion; what I should have is $\frac{\partial \dot{\bar{p}}_t^N}{\partial \bar{p}_{t_0}^N} \Delta t$ we will not, we will ignore the higher order terms over here and this one is going to be $1 + \frac{\partial \dot{\bar{q}}_t^N}{\partial \bar{q}_{t_0}^N} \Delta t$ both evaluated at t_0 . This quantity is going to be $\frac{\partial \dot{\bar{q}}_t^N}{\partial \bar{p}_{t_0}^N} \Delta t$ and this is going to be $\frac{\partial \dot{\bar{q}}_t^N}{\partial \bar{p}_{t_0}^N} \Delta t$, the N has now come as a subscript t_0 , correct.

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$$\begin{aligned}
 J(t, t_0) &= \begin{vmatrix} 1 + \frac{\partial \dot{q}^N}{\partial \dot{p}^N} \Delta t & \frac{\partial \dot{q}^N}{\partial \dot{q}^N} \Delta t \\ \frac{\partial \dot{q}^N}{\partial \dot{p}^N} \Delta t & 1 + \frac{\partial \dot{q}^N}{\partial \dot{q}^N} \Delta t \end{vmatrix} \\
 &= 1 + \underbrace{\left(\frac{\partial \dot{q}^N}{\partial \dot{p}^N} + \frac{\partial \dot{q}^N}{\partial \dot{q}^N} \right)}_{=0} \Delta t + \mathcal{O}(\Delta t^2) \\
 J(t, t_0) &= 1 + \mathcal{O}(\Delta t^2)
 \end{aligned}$$



So, 1 plus del q N dot sorry, del p N t 0 del p N t 0 plus del q dot N t 0 del q N t 0; there are higher order terms which we will not consider. So, if we just consider this times this; then this is going to give you this result, right. But we did this, this is equal to 0. So, therefore, J of t comma t 0 is 1 plus order delta t square; there is no delta t term that survives this equation.

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$$\frac{dJ}{dt} = \lim_{\Delta t \rightarrow 0} \frac{J(t,0) - J(t_0,0)}{\Delta t} = 0$$


 $t=t_0$


 $t=t$

$$\Rightarrow \frac{dJ}{dt} = 0 \quad \Rightarrow \quad d\vec{x}_t^N = d\vec{x}_0^N$$

Flow of probability \rightarrow incompressible flow
↓
there is no loss in probability.

$$i \frac{\partial}{\partial t} \int f(\vec{x}^N, t) = \hat{L}^N f \quad \int f(\vec{x}^N, t) = e^{-i \hat{L}^N t} \int f(\vec{x}^N, 0)$$



So, one can therefore, write down J of t comma 0 the Jacobian; you start from time 0 to time t is J comma t comma t_0 J comma t_0 comma 0 , right. So, this becomes J of t_0 comma 0 1 plus order Δt square. So, dJ/dt is equal to limit of Δt to 0 J comma minus which is going to be 0 , right.

Therefore, it follows that dJ/dt is equal to sorry, dJ/dt is going to be 0 , which would imply that d of X^N comma t is going to be d of X^N comma 0 . Therefore, the volume, this volume element that you considered at t equal to t_0 and at t equal to t are the same.

So, the volume is preserved. The flow of probability and this essentially is another statement that, this is the conservation of probability; therefore the probability cannot be lost, it does not leak out of the volume. Therefore, this flow of probability is essentially an incompressible flow; which means that, there is no loss in probability.

So, we looked at the probability N particle probability density and we said that, this equation, the dynamical equation for the evolution of this obeys the Liouville equation of motion is essentially the Liouville's equation of motion; the solution to this equation is sorry, there has to be an i here, e to the power i L hat N times t rho X N of 0, right.

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$\rho(\vec{x}^N, t)$
 $\mathcal{H}^N(\vec{x}^N) = E$

Probability flow is incompressible

$\mathcal{H}^N(\vec{x}^N) = E$ (constant) → Isolating

Time reversal symmetry
 Hermitian operator
 Oscillatory in nature in incompressible flow in the phase space

Expectation values of Dynamical variables $A(t)$

Expectation →

$$\langle A(t) \rangle = \int d\vec{x}^N A(\vec{x}^N) \rho(\vec{x}^N, t) = \int d\vec{x}^N A(\vec{x}^N) e^{-i\hat{L}^N t} \rho(\vec{x}^N, 0)$$

$$= \int d\vec{x}^N \rho(\vec{x}^N, 0) e^{i\hat{L}^N t} A(\vec{x}^N) = \int d\vec{x}^N A(\vec{x}^N, t)$$

Further we established a little while ago that, the flow, probability flow is incompressible; which essentially means that there is no loss in probability, right. So, how does one visualize this? You can imagine that there is a hyper surface, which is defined by this conservation of energy in the 6 N dimensional phase space. So, I can imagine that there is a hyper surface, which is defined as by this equation with the right hand side E is a constant.

Now, I can consider a small patch, which will denote the initial conditions of all my particles, right. And as the system evolves, this patch slowly and slowly evolves throughout the phase

space; because there are several trajectories, this is when if you wait sufficiently long enough, it encompasses the whole of the phase space, it is like spreading of an ink drop in a liquid.

The Liouville equation has several properties; number 1 is this is obeys the time reversal symmetry, because the underlying microscopic dynamics obeys the Hamilton equation of motion which are time reversal, therefore this equation obeys time reversal symmetry, right.

It is a Hermitian, the Liouville operator is a Hermitian operator and if we look at the nature of the solution, particularly this term; this essentially tells you that the solution is always oscillatory in nature. Therefore, one must understand that this equation does not describe the irreversible decay of the system to a unique equilibrium state. So, you one must start off with the equilibrium state from the very beginning itself.

So, as time evolves, in this picture that we have tried to establish that, this is an incompressible flow, incompressible flow in the phase space and therefore, if you start off with a small patch of initial conditions; it is going to evolve as time progresses the trajectories are going to evolve, so that it slowly and slowly covers the whole of this phase space, right.

Now, what does this mean? So, is this always guaranteed right; that is the point that we what, which we want to discuss. Now, before we try to discuss the consequence of what we just described that, if we start off from a small patch of initial conditions, it slowly as the time evolves, if you have sufficiently long enough time; there is a randomness already inbuilt, because in this initial conditions therefore, the whole thing covers the whole of the phase space. And what is the consequence of that before we describe that?

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Hermitian operator
Oscillatory in nature
incompressible flow
in the phase space

Expectation values of Dynamical variables $A(t)$

Expectation \rightarrow $\langle A \rangle = \int d\vec{x}^N A(\vec{x}^N) \rho(\vec{x}^N, t) = \int d\vec{x}^N A(\vec{x}^N) e^{-i\hat{L}t} \rho(\vec{x}^N, 0)$

Phase space \rightarrow $= \int d\vec{x}^N \rho(\vec{x}^N, 0) e^{i\hat{L}t} A(\vec{x}^N) = \int d\vec{x}^N A(\vec{x}^N, t)$

$$i \frac{\partial A(\vec{x}^N, t)}{\partial t} = -\hat{L}^N A(\vec{x}^N, t)$$

$\vec{x}^N = E$

$\langle A \rangle_T = \lim_{T \rightarrow \infty} \frac{1}{T} \int_0^{t+T} A(t) dt$

$A(t) \leftarrow$




So, we want to, I want to just write down what we are mainly interested in. We are interested in typically our expectation values of dynamical variables, right. And say A of X^N right; well not X^N , we are typically going to be interested in dynamical variables A of t , right.

Then the average of A of t is defined as d of X^N , this is the measure A of X^N rho of X^N comma t right, which is going to be d of X^N A of X^N e to the power minus i . So, this is kind of the Schrodinger picture, where the operator does not carry the time evolution; but it is a probability density which carries the time evolution.

We can write down alternatively the same expression for average of this, which is the Heisenberg picture, where I am going to have A of; I am going to take this term, which

becomes $\langle X \rangle_N$ as a function of t , where now this dynamical variable based an evolution equation which is \hat{L} sorry, just I am in a little bit clumsy $\langle X \rangle_N$, right.

Anyway this is just as a remark that one should remember; but we are mainly interested in an equation of this form, where I define the expectation of a dynamical variable in terms of the probability density.

Now, coming back to the original question that we posed that, with the picture that we have developed for ρ of X and t ; we realize that first of all this vector is the tip of this vector is essentially bound to move on the surface which is defined by the conservation of energy, right.

Such surfaces are what are called isolating integrals. So, for an N particle system, this is the only isolating integral that we can have. So, in the phase space, an isolating integral would come would consist of a closed surface; there are other type of integrals which are called non isolating integrals.

So, your conservation, your constants of motion, your conservation of momentum, conservation of angular momentum and your conservation of energy of these, only this one forms the isolating integral. And this is therefore, very very important in what we are going to discuss. Now, clearly let us draw this thing little bit over here; I have this surface which I have again, let us just write down this as this. And as I said that as the system evolves, it slowly and slowly fills up the whole of the phase space, right.

So, what does it mean for us? We cannot observe these quantities right, we cannot observe X of N experimentally; we are rather interested in a limited set of dynamical variables A of t , it can be the total energy, it can be the total momentum whatever that is, we are only limited to observing this.

Now, as we have said that, clearly this is one possible way of defining the expectation value; there is yet an alternative way of defining this expectation value which would say that, if I

have the time series of A, which means I measure A as a function of time, then I can define that a different average sorry, with limit of t to capital T to infinity.

So, essentially this means that, you measure this quantity for a large time window and essentially you calculate the average and this is going to be another average which you will write down A of t.

This average, so here it is no longer a function of t, but it is just this. This average is defined in terms of your phase space; why, because you are using the phase space density over here and this is purely a time average, right. Now, the question is, is this equal to the phase space average, right?

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$\langle A \rangle_T = \frac{1}{T} \int_{t_0}^{t_0+T} A(t) dt$
 Time average
 $\langle A \rangle = \frac{\int A(\vec{x}) \rho(\vec{x}) d\vec{x}}{\int \rho(\vec{x}) d\vec{x}}$
 Ergodic theorem
 $\langle A \rangle_T = \langle A \rangle \rightarrow \text{system is ergodic}$
 $\rho(\vec{x}) = \frac{\delta(\vec{x}^N - \vec{x}^N(t))}{T}$
 $\Omega(E) = \int d\vec{x}^N \delta(\vec{x}^N - E)$



So, now that we have two averages that is defined; one is the time average, average A of t and the other one is the phase space average. The question is whether they are, both of these are equal and when are they equal? And the answer to that, comes from the ergodic theorem; the ergodic theorem essentially tells you that not only that the time average should exist, but if the system is ergodic, then the two averages are equal.

So, this happens when the system is ergodic or alternatively the flow in the phase space is an ergodic flow. There are two kinds of flow generally which is considered in the phase space which is an, but we will not worry about that right now. So, our point is that, if the flow is ergodic; then the time average and the phase space average are equal. But what does this mean?

Let us go back to the picture, where we were visualizing the phase space and our phase space trajectories are all covered up the phase space. Now, if you consider a small region R as indicated over here by the black closed surface and you ask that, what is the probability that the state which is denoted by X_N is in this region R ? Then since the whole of the phase space is completely filled, therefore the answer to that question is essentially that probability.

Let us say is equal to σ_R divided by σ_E , where σ_R is the surface area contained by this black contained within R , and σ_E is the total surface area. σ_E is formally defined as d of X_N delta of $H_N X_N$ minus E . So, essentially the delta function guarantees that the tip of this vector, this way measure its can only takes account, takes into account the surface area contained within this volume, right.

Now, since the flow is ergodic, the time average is equal to the phase space average; therefore this probability also means that, this is equal to the time that the system spends in this region R to the total observation time. So, when the flow is ergodic, the in equal areas in the phase space, the system will spend equal amount of time.

If there are no isolating integrals for an N particle system; if there are no isolating integrals other than the conservation of energy, then the flow is ergodic. There can be other isolating

integrals and find for an any N particle system; there can be other isolating integrals other than the conservation of energy and finding the number of isolating integrals is really really a very difficult job, right.

Now, let us come back to this expression. So, once I have this probability, then you see this probability I can write down as 1 over sigma E integral d X sorry, not d X N; but essentially an integral over the surface area in the region R, right. You can write down in terms of X N; but you have to also include delta H N minus X N and the integral is over the region R, right.

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Ergodic theorem

Time average $\langle A \rangle_T = \langle A \rangle \rightarrow$ System is ergodic

$$\vec{x}^N \text{ Prob} = \frac{\Omega(R)}{\Omega(E)} = \frac{\gamma(E)}{T}$$

$$\Omega(E) = \int_{\vec{x}^N} \delta(\mathcal{H}(\vec{x}^N) - E)$$

$$\text{Prob} = \frac{1}{\Omega(E)} \int_R d\vec{x}^N$$

→ Ordinary State

$$\int d\vec{x}^N = \frac{1}{\Omega(E)}$$

→ Microcanonical Ensemble → Isolated System

$$\langle A \rangle = \frac{1}{\Omega(E)} \int d\vec{x}^N A(\vec{x}^N) \delta(\mathcal{H}(\vec{x}^N) - E)$$


Now, if you recall your, when we discussed continuous random variables and probability densities; we said that the probability of finding a variable x within a range or within an interval R was essentially over the interval d X and rho X, right. And surprisingly if we just look at these two; then this has a similar form and we immediately read off that rho of X N is

$\frac{1}{\sigma_E}$, where σ_E is a surface area and defined by the isolating integral H of X . N is equal to E .

This simple looking expression that we have come to, essentially tells you that all the points in the phase space are equally likely to be visited. It is also a point, the point to be noted is that, this expression does not contain time anymore; because we have waited sufficiently long enough for the system to evolve, so that the phase space is completely filled and we have therefore, reached a stationary state, correct.

This equation is what is called a micro canonical ensemble and the average of any dynamical variable is now $\int dX dN \delta(H(X,N) - E) \frac{1}{\sigma_E}$. The delta function once again ensures that it is a surface which is only matters here and not the volume. We shall get rid of this, we shall see later on how to take, how to get around this difficulty, correct.

It is also worth noting that when we visualize this picture over here of the phase space; we said there is no other not we, I mean when we visualize this picture, essentially this also means that there are no other interactions present in the system. So, you do not have; you just have your system, there is nothing else.

So, therefore, this would correspond to an isolated system, what we consider in thermodynamics right. An isolated system in thermodynamics essentially means a micro canonical ensemble in terms of probability or statistics or statistical mechanics for that sake, good.

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Entropy $S = -k_B \sum_j p_j \ln p_j$ $\rho(\vec{x}^N) = \frac{1}{\Sigma(E)}$

$$S = -k_B \int d\vec{x}^N \rho(\vec{x}^N) \ln \frac{\rho(\vec{x}^N)}{C_N}$$

 $\int d\vec{x}_1 d\vec{x}_2 \dots d\vec{x}_N$

$$S = k_B \ln \frac{\Sigma(E)}{C_N}$$

$$\Sigma(E) = \int d\vec{x}^N \delta(\mathcal{H}(\vec{x}^N) - E)$$



So, now that we have this probability density, what do we want to do? The bridge is given by the statistical entropy or we will just write down entropy S as minus sum over $p_j \ln p_j$; except now we have minus integral $d\vec{x}^N$, oops $\rho(\vec{x}^N) \ln \rho(\vec{x}^N)$ divided by C_N . But clearly what we are interpreting is entropy, does not have the dimension of entropy. So, what we introduce is a Boltzmann factor S , right.

If I introduce $\Sigma(E)$, rho if we use this expression for rho of \vec{x}^N is equal to $1/\Sigma(E)$; then you see your entropy is $k_B \ln \Sigma(E)/C_N$. Note that reason we have introduced the C_N factor over here is because this surface area is dimension full; because this surface area has $dp_1 dp_2 \dots dp_N$ so forth and we shall later on see what C_N is going to be.

Now, coming back to this, this quantity is called the structure function and is defined as $\int dX^N \delta(H(X) - E)$. And you can imagine that for a 6 N dimensional space, it is a notoriously difficult quantity to evaluate. So, what do we do?

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$\Sigma(E)$
 $\Sigma(E, V, N)$
 $\Omega_{\Delta E}(E, N, N)$
 $S = k_B \ln \frac{\Omega_{\Delta E}}{C^N}$
 Consider $0 \leq X(X^N) \leq E$

$\Omega_{\Delta E}(E) = \int_{R} dX^N \delta(E) \Delta E$
 $\rho(X^N) = \frac{1}{\Omega_{\Delta E}}$
 $X(X^N) = E$



Well we start off by saying that look, instead of considering that the system is strictly at an energy level E ; I can also consider a spread in the energy level, so that I replace this by E plus delta E . If that is the case, then you can think then this surface area that we are considering is now replaced by the volume which is contained within this shell defined by $E \leq H \leq E + \Delta E$.

So, that I have now $\Omega_{\Delta E}$ as a function of E as $\int dX^N$ over this region and your probability density ρ of X^N is just going to be $1 / \Omega_{\Delta E}$, so that your entropy is going to be $k_B \ln \Omega_{\Delta E} / C^N$, right. If your ΔE is small enough, this can be

approximated by $\sigma(E) \Delta E$ right, not otherwise; we shall also remove this restriction on ΔE .

So, now that we have replaced $\sigma(E)$ by the volume which is contained within this shell of energy E and $E + \Delta E$; even this volume is also very difficult to calculate. Before we go ahead with this argument that, how we can replace this; what we want to say about two points is that, this $\sigma(E)$ that we originally started off with, essentially that represents the surface area of the isolating, it defined by the isolating integral is also a measure of the total number of microstates of the system, right.

What we have been calling is $\Omega(E)$ as states are essentially the microstates of the system. And in principle, although we have been denoting it with $\sigma(E)$; this for a hydrostatic system, for an N particle system which physically occupy a certain volume in space and has certain particle number is more explicitly written as $\sigma(E, V, N)$ and so, is $\Omega(E, V, N)$, right.

So, now what we want to look at is, how do I replace this cumbersome calculation of the shell in the hyper surface by something more easier to do. For that again, we consider this inequality, where now my system is allowed to have energies all the way from 0 to E .

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$$S = k_B \ln \frac{\Omega(E)}{C N^N}$$

Consider $0 \leq X(\vec{r}^N) \leq E$

Outermost shell $E \leq E + \Delta E \quad \Omega_{\Delta E}(E, V, N)$

$$\Omega(E, V, N) = \sum_i \Omega_{\Delta E}(E_i, V, N)$$

$$\int_{\Delta E} \Omega(E, V, N) \leq \frac{E}{\Delta E} \Omega_{\Delta E}(E, V, N)$$

$\frac{E}{\Delta E}$ number of shells

So, essentially you define this hyper surface which is denoted over here. And the surface the bounding surface is defined by the energy E ; whereas the system is allowed to have energies from 0 to E . What you now do is essentially, you break up this volume into small small shells of energy of width ΔE . So, let me just quickly try to schematically draw them; this is also ΔE , again you have an inner. So, you keep on doing it. So, there you have E over ΔE number of shells.

The outermost shell which is contained between; so let us write here outermost shell which is contained between E and E plus ΔE has the volume $\Omega_{\Delta E}(E, V, N)$. Why am I suddenly, suddenly interested in this or because this is exactly that quantity we have been dealing with earlier. Therefore, if you look at it carefully; so this is the shaded volume that we

are referring to. Now, the total volume $\Omega(E, V, N)$, which is contained by this hyper surface is sum over i $\Omega_{\Delta E}(E, V, N)$.

But if you look at this expression, it is very very evident; even this pictorial representation is very very evident that, this quantity, the total volume which is contained within this hyper surface is definitely more than the shaded area, right. So, therefore, we can write down this as $\Omega_{\Delta E}(E, V, N) < \Omega(E, V, N)$; $\Omega_{\Delta E}$ over ΔE number of shells, if I multiply this by ΔE , then the total volume is less than this volume, right.

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$\frac{\Omega(E, V, N)}{\Delta E} \approx \frac{\Omega(E, V, N)}{\Delta E} = \frac{\Omega(E, V, N)}{\Delta E}$ Extensive
 Entropy
 $\ln \Omega_{\Delta E} \leq \ln \Omega \leq \ln \frac{E}{\Delta E} + \ln \Omega_{\Delta E}$
 $\frac{E}{\Delta E} \sim N$
 $\ln \Omega \sim N$
 $\ln \Omega_{\Delta E} \sim O(N)$
 $\ln \frac{E}{\Delta E} \sim O(N)$
 $\ln \Omega \sim O(N)$
 $\ln \Omega_{\Delta E} \approx \ln \Omega(E, V, N)$
 $S = k_B \frac{\ln \Omega(E, V, N)}{C_N}$
 $C_N = h^{3N}$ distinguishable particles
 $= N! h^{3N}$ for indistinguishable particles



So, now if you take a log $\Omega_{\Delta E}$ is less than $\ln \Omega$, which is less than $\ln \frac{E}{\Delta E} + \ln \Omega_{\Delta E}$. Note that this is the one which enters the entropy, right. On the other hand; so this is a total number of microstates, log of that and is therefore is an extensive

quantity. In contrast, E is an extensive quantity and therefore, $E/\Delta E$ would scale as N ; whereas $\ln \Omega$ would scale as $\ln N$.

So, if you now take the limit, the thermodynamic limit of N to infinity, large number of particles; then you see in this inequality, this term drops out of the computation, because this is only $\ln N$ of the order of $\ln N$, whereas this term is N , this term is N . So, not I mean; what I mean to say is, of the order of $\ln N$ and this term is of the order of $\ln N$. So, this term drops out from this equation and you have very nicely $\ln \Omega/\Delta E$ is less than $\ln \Omega/\Delta E$, right.

So, that in the thermodynamic limit, the $\ln \Omega/\Delta E$; what we have been using in place of the entropy is $\ln \Omega(E, V, N)$, the total volume contained within the phase space, right. So, we rewrite our equation our expression for entropy as $k_B \ln \Omega(E, V, N)/C N$. We shall come back to $C N$; but right now it suffices to say that $C N$ is equal to $h^3 N$ for distinguishable particles and is $N!$ for indistinguishable particles.

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Outermost shell $E \leq E + \Delta E$ $\Omega_{\Delta E}(E, V, N)$

$$\Omega(E, V, N) = \sum_i \Omega_{\Delta E}(E_i, V, N)$$

$$\int d\vec{x}^N$$

$$\frac{\int d\vec{p}_1 d\vec{q}_1 d\vec{p}_2 d\vec{q}_2}{\bar{p} \times \bar{q}} \text{ Action}$$

$$\Omega_{\Delta E} \approx \Omega(E, V, N) \approx \frac{E}{\Delta E} \Omega_{\Delta E}(E, V, N) \rightarrow \text{Extensive}$$

Entropy

$$\ln \Omega_{\Delta E} \approx \ln \Omega \approx \ln \frac{E}{\Delta E} + \ln \Omega_{\Delta E}$$

$\frac{E}{\Delta E} \sim N$
 $\ln \Omega \sim N$

$\ln \Omega_{\Delta E} \approx \ln \Omega \approx \ln \Omega_{\Delta E}$



h is the Planck's constant and that is not very surprising to figure out why h comes in; because if you look at the measure in the phase space, it is d of $X N$. If you expand this, then this is $d p_1 d q_1, d p_2 d q_2$. So, the product of p times q has a dimension of action, same quantity that as h as the Planck's constant. So, essentially you become, it becomes it non dimensionalize this volume by h to the power $3 N$.

The introduction of this h to the power $3 N$ and the N factorial is clearly something which is done by hand in classical statistical mechanics. We have no way of introducing it very naturally in the theory; we shall see later on how quantum statistical mechanics does it.