

Our Mathematical Senses

The Geometry Vision

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Lecture-45

Video 9D: 2D Fundamental theorem of projective geometry

So now let's look at the two-dimensional version of the fundamental theorem of projective geometry. So our initial goal was to understand projectivities between planes. In particular, how many degrees of freedom are there in the set of projectivities between planes, which is another way of saying what all changes as we shift perspective. So this is our attempt to address that initial question. So what is the fundamental theorem saying in 2D? Well, it's saying the following. Let's take two planes, π and π' , sitting in P^3 .

And these are, of course, extended planes because they're sitting in P^3 . Let's let P, Q, R and S be four points in π . And let's let P', Q', R' and S' be four points in π' . These can be any two ordered sets of four points with the restriction that no three are collinear.

In either set of four points, no three are collinear. In other words, they should really be able to form a quadrilateral of some sort of quadrilateral. If three are collinear, that's no good. Then we'll get something like this and they won't really form a quadrilateral. So that's the only restriction.

Otherwise we have full freedom in choosing these four points in each of these two planes. Now in this situation, the fundamental theorem states that there exists a unique projectivity from π to π' , which takes P to P' , Q to Q' , R to R' and S to S' . There's a unique projectivity from π to π' , which maps these four points onto those four points in order. The order matters here. If I switched, there'll be one projectivity taking these guys in this order.

But if I wanted R to map to S' and S to map to R' , I'd also be able to get a projectivity that did that. And that would also be unique. So to prove this, I'm going to follow a proof from Norman Wildberger's video lectures, actually. It uses the fundamental theorem of projective geometry in 1D. So the key to this proof is to first extend the line through PQ and the line through SR .

Those are going to intersect at a point A . Similarly, let's extend $P'Q'$ and $S'R'$. Those are going to intersect at a point A' . Now by the fundamental theorem, there exists a projectivity taking P, Q and A to P', Q' and A' . Remember, the fundamental theorem holds in P^3 .

Between any two lines in P^3 , we can take three points here and three points here, and we can find a projectivity taking these three to these three. So we're just literally applying the fundamental theorem, taking P to P' , Q to Q' and A to A' . It's a projectivity from this line to this line. But we can extend this projectivity to a projectivity of planes, which we'll call γ . We just need to choose planes that contain each of the intermediary lines, but which don't intersect any of the points, any of the centers of perspective.

So that's relatively easy to do. There's lots of degrees of freedom there in choosing those planes. So let's take a projectivity of planes γ from π to some plane π^* . And it needs to take P to P' , Q to Q' and A to A' . And we just want to make sure that π^* is not equal to π' .

Again, we have a lot of freedom in choosing those planes. So we can choose the final plane π^* such that it's not equal to π' . So it'll look something like that. So we have a projectivity γ now, which maps π to π^* and takes these three points to these three points. So notice that in this, under this projectivity γ , it's going to take S and R somewhere, somewhere in this plane π^* .

But this line, it's going to take this line SR to some line going through A' . And on that line, it's going to take S to some point S^* and R to some point R^* . So we get these new points S^* and R^* , which do form a line that hits A' . And they live somewhere in π^* . So the points R^* , which is just $\gamma(R)$ and S^* , which is just $\gamma(S)$.

Yeah, they lie on π^* . But the thing to notice here is that R^*, S^* and S', R' , this is S', R' is a line in the plane π' , they're going to be coplanar because they share a point A' . So they're going to be coplanar. And as a result, we can look at the intersection of S', S^* and R', R^* . So let's call that

intersection O .

And we can look at the perspective centered at O from the plane π to the plane π' . And that's guaranteed to take R to R' . It's going to take S to S' . But it's also going to fix everything on the intersection between these planes. It's going to fix P , it's going to fix Q .

So all in all, it's actually taking this quadrilateral down to this quadrilateral. And what happens when we compose it with our map f , sorry, with our map γ ? Remember, our map γ took π to π' . So if we do γ and follow it with this f , we end up with a map from π to π' . And it does exactly what we want. It's going to take P to P' , Q to Q' , S to S' , and R to R' .

So it's the desired projectivity that we were seeking. So that takes care of the existence of a projectivity. And we still have to prove the uniqueness of it. But we'll do that in the next video.