

An Introduction to Hyperbolic Geometry

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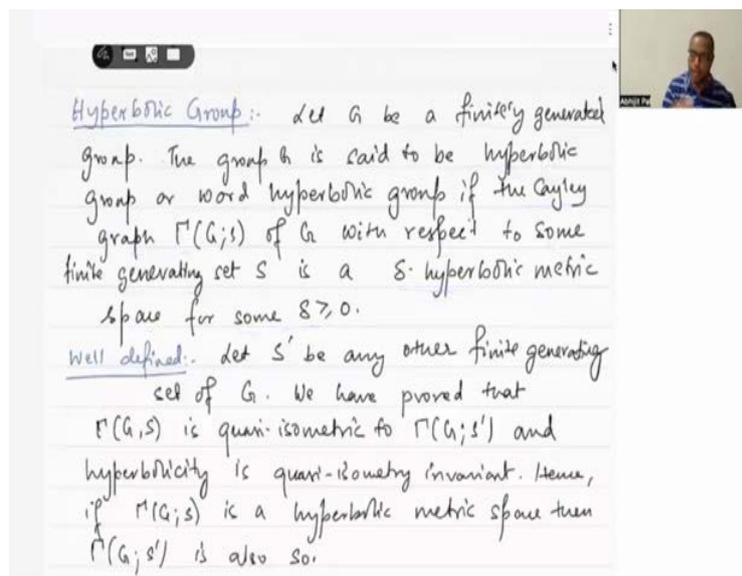
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Lecture – 37

An Introduction to Hyperbolic Groups and Their Finite Presentations

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Hello! In this lecture, we will delve into the concept of hyperbolic groups and proceed to prove that every hyperbolic group is finitely presented. Let's begin by defining what a hyperbolic group is.

A hyperbolic group, or more specifically, a word hyperbolic group, is a finitely generated group with a particular property: the Cayley graph of this group, with respect to some finite generating set S , forms a δ -hyperbolic metric space for some non-negative number δ .

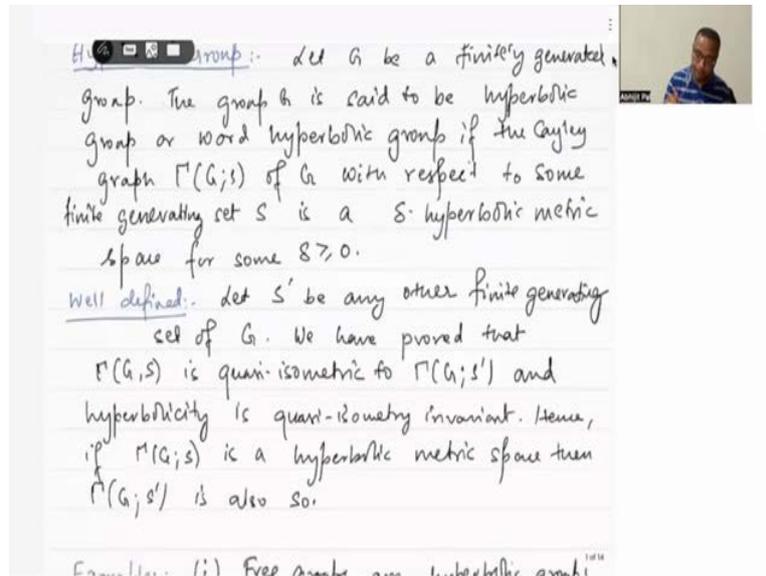
In other words, given any finitely generated group G , one can construct its Cayley graph based on the generating set S . If this Cayley graph behaves as a hyperbolic metric space (as defined in geometric group theory), then the group G is classified as a hyperbolic group.

Now, an important question arises: Is this definition well-defined?

There can be many generating sets for the finitely generated group G . Now, suppose S' is another finite generating set for this group G . We have already established that the Cayley

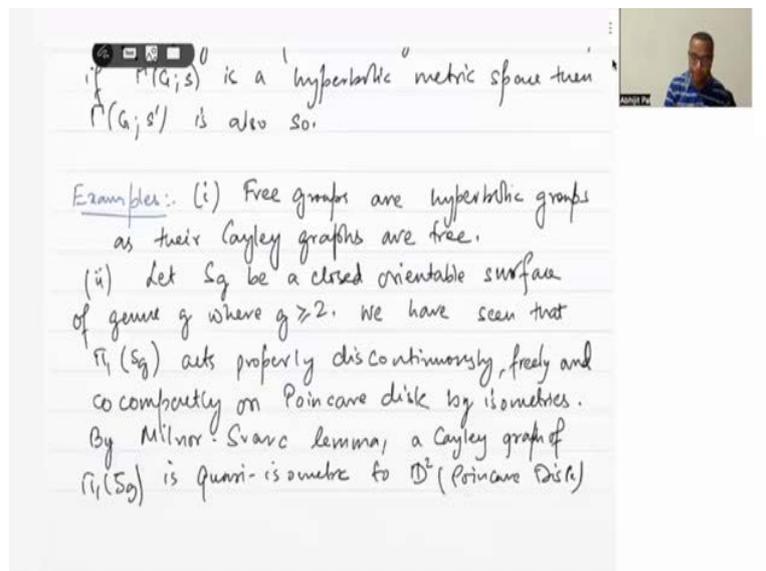
graph of G with respect to S is quasi-isometric to the Cayley graph of G with respect to the generating set S' . In fact, in our previous lecture, we demonstrated that hyperbolicity is an invariant under quasi-isometry.

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Therefore, if the Cayley graph $\Gamma(G, S)$ is a hyperbolic metric space, then the Cayley graph $\Gamma(G, S')$ will also be hyperbolic. This proves that the definition of hyperbolicity is well-defined in the sense that, regardless of which finite generating set we choose, the corresponding Cayley graphs will all be hyperbolic metric spaces.

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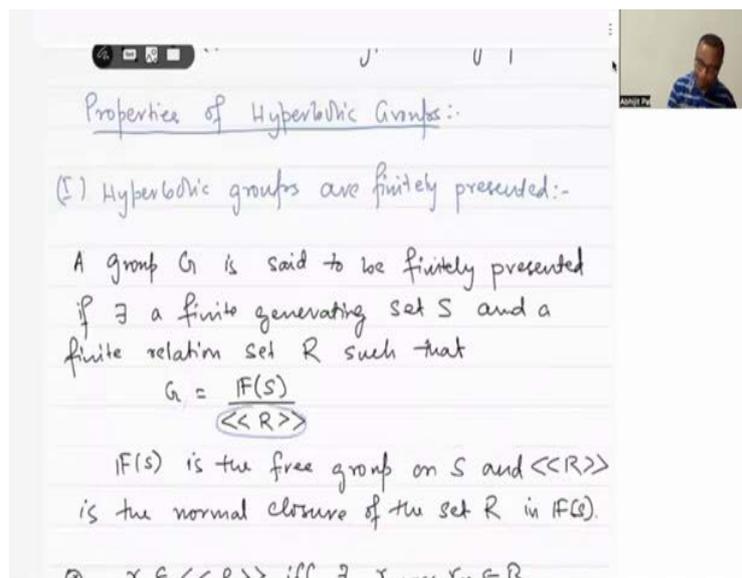


For instance, consider free groups of any rank. These free groups are hyperbolic because their Cayley graphs exhibit free structure. Now, let's take the example of a closed orientable surface of genus g , where $g \geq 2$. We know that the fundamental group of such a surface acts properly discontinuously, freely, and co-compactly by isometries on the unit disk model of the hyperbolic plane. That is the key observation here.

By the Milnor-Švarc Lemma, if we consider the Cayley graph of this fundamental group with respect to some finite generating set, it will be quasi-isometric to the Poincaré disk, which is itself a hyperbolic metric space. Since hyperbolicity is a quasi-isometry invariant, the Cayley graph of this fundamental group will also be a hyperbolic metric space.

Thus, the fundamental group of a surface of genus g , where $g \geq 2$, is indeed a hyperbolic group.

(Refer Slide Time: 04:04)



Next, we will prove that hyperbolic groups are finitely presented. Before diving into the proof, let's recall the definition of a finitely presented group. A group is said to be finitely presented if there exists a finite generating set S and a finite set of relations R such that the group can be expressed as a quotient. Specifically, the group is the quotient of the free group generated by S , and the denominator consists of the normal closure of the set R , where R is a finite set.

In other words, this means that the group can be described with a finite number of generators and a finite number of relations among those generators, which greatly simplifies its structure

and the way it can be studied or manipulated algebraically.

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if \exists a finite generating set S and a finite relation set R such that

$$G = \frac{F(S)}{\langle\langle R \rangle\rangle}$$

$F(S)$ is the free group on S and $\langle\langle R \rangle\rangle$ is the normal closure of the set R in $F(S)$.

② $\gamma \in \langle\langle R \rangle\rangle$ iff $\exists r_1, \dots, r_n \in R$ such that $\gamma = \prod_{i=1}^n x_i r_i x_i^{-1}$.

Theorem: A hyperbolic group G is finitely presented.

Proof: By definition of hyperbolic group, the group G is finitely generated. let

Now, note that if we take any element R belonging to the normal closure containing r , there will exist finitely many elements, say r_1, r_2, \dots, r_n , such that R can be expressed as the product of conjugates of these r_i . In other words, $R = \prod (x_i r_i x_i^{-1})$, where i runs from 1 to n .

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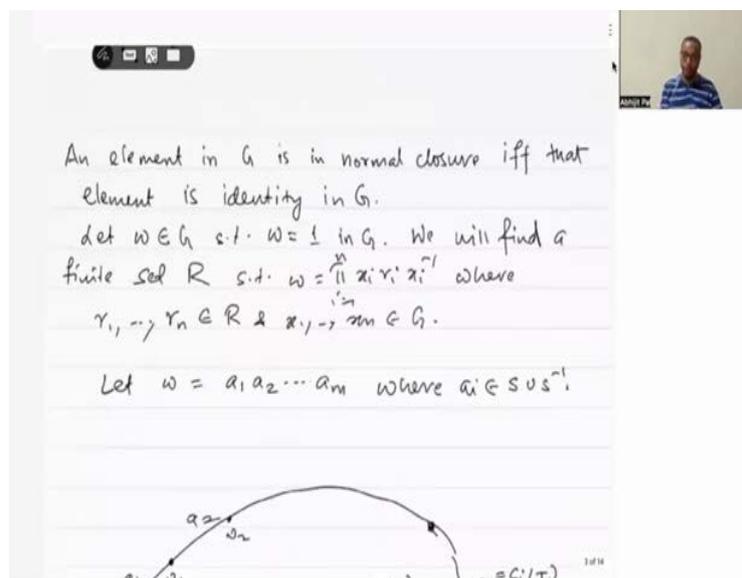
Conversely, if an element can be written as the product of such conjugates, then R must belong to the normal closure containing the set R . This is a straightforward observation, something

that is usually encountered while studying group theory and normal closures.

Now, let's state the theorem: A hyperbolic group is finitely presented.

By the very definition of a hyperbolic group, the group G is finitely generated. Let S be a finite generating set of G . We will build upon this foundational aspect as we move forward in the proof. This key fact ensures that the group structure is well-defined and manageable, paving the way for further analysis.

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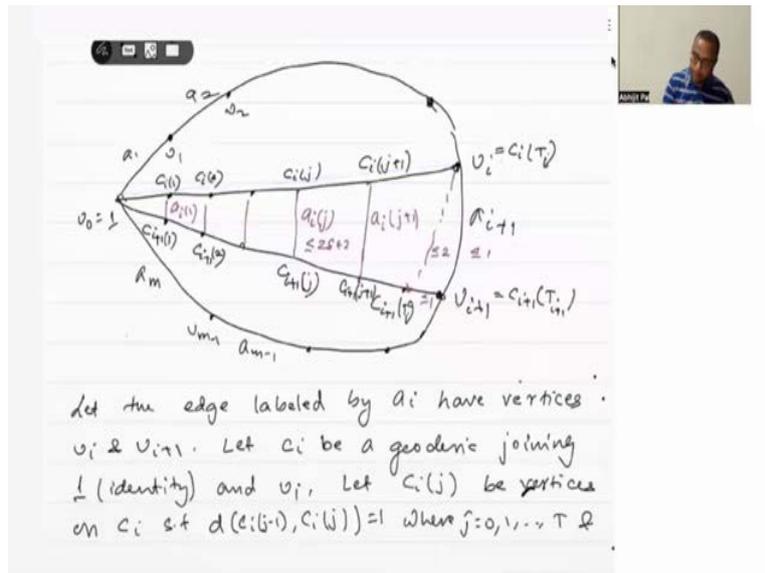


First of all, let's note that an element in G belongs to the normal closure only if it is the identity element in G . So, suppose we take an element w which belongs to the denominator, i.e., the normal closure. In that case, that element must be the identity element in G . The converse also holds true, if an element is the identity element in G , then it belongs to the normal closure.

Therefore, there must exist elements r_1, r_2, \dots, r_n in R such that this w can be expressed as the product of conjugates $x_i r_i x_i^{-1}$. Now, let's express w as $w = a_1 a_2 \dots a_m$, where each a_i belongs to the generating set S , meaning either $a_i \in S$ or $a_i^{-1} \in S$. This implies that each a_i is either an element of S or its inverse. Therefore, w is represented as a product of elements from $S \cup S^{-1}$.

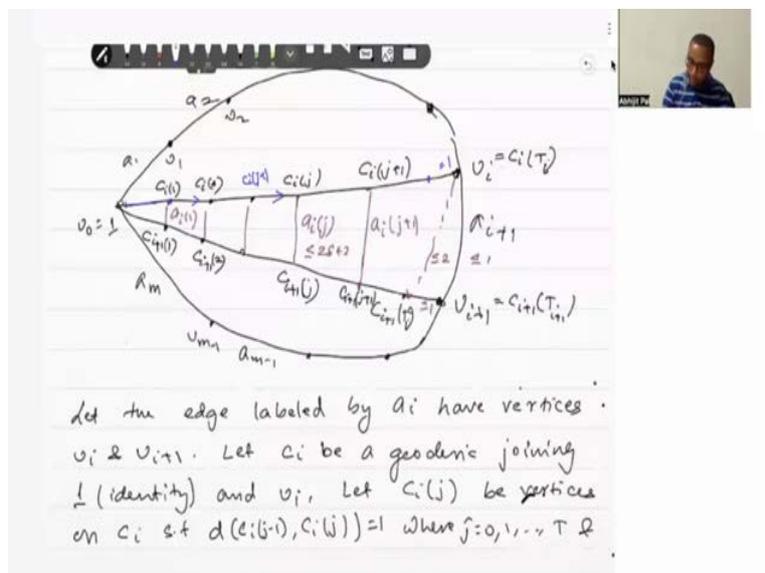
Since $w = 1$, it represents a loop. Let's denote this loop as v , which corresponds to w . Now, w starts from the identity element, 1 , and forms an edge in the Cayley graph. The first vertex in this loop is v_1 , and there is an edge between 1 and v_1 , labeled by a_1 . The next vertex is v_2 , with an edge between v_1 and v_2 labeled by a_2 , and this pattern continues.

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Each edge between vertices v_i and v_{i+1} is labeled by a_{i+1} . Now, what we do next is, for each vertex v_i , we take a geodesic c_i that joins the identity element and v_i . This means that c_i is the geodesic joining 1 and a_i .

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So, let's proceed with this construction. For every index i , we obtain a corresponding geodesic. Now, note that the distance between any two consecutive vertices, v_i and v_{i+1} , is at most 1, since the length of the edge between them is exactly 1. This is an important observation.

Next, let us introduce the notation c_{ij} , where c_{ij} represents vertices on the geodesic c_i , and the

distance between consecutive vertices $c_{i(j-1)}$ and c_{ij} is exactly 1. Thus, we can split the geodesic c_i into segments, as follows:

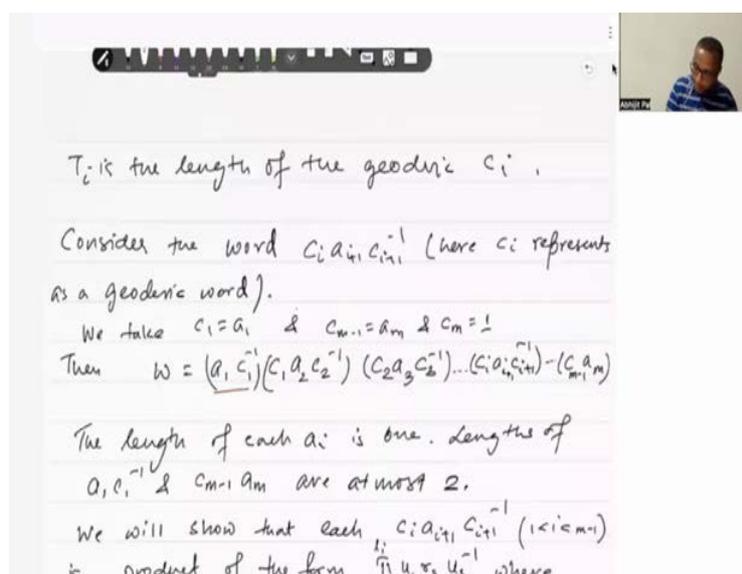
- Start by taking c_{i1} , such that the distance between the identity element and c_{i1} is precisely 1.
- Then, for each subsequent point, the distance between $c_{i(j-1)}$ and c_{ij} remains 1. Eventually, for the last point, say $c_{i(j_i)}$, we arrive at vertex v_i .

Now, observe that for each vertex v_i , the distance between the identity element and a_i is a natural number, which means that the distance between consecutive vertices $c_{i(j-1)}$ and c_{ij} is always exactly 1.

Thus, for all i , you follow this same construction, and you'll end up with a clear picture of the structure. To complete the picture, join c_{i1} and $c_{(i+1)1}$ by geodesics. These are denoted by c_{ij} and $c_{(i+1)j}$, and we label each geodesic with a_{ij} .

This setup creates a well-structured framework of geodesics and vertices, where each edge is labeled accordingly, and the distances between the points are consistently maintained as per the geodesic properties.

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Now, let's focus on constructing this particular word. Consider the word $c_i a_{i+1} c_{i+1}^{-1}$, where c_i represents a geodesic word. What we do here is first trace along c_i , then move to a_{i+1} , and finally return via c_{i+1}^{-1} . This forms a loop, represented as $c_i a_{i+1} c_{i+1}^{-1}$, within the Cayley graph.

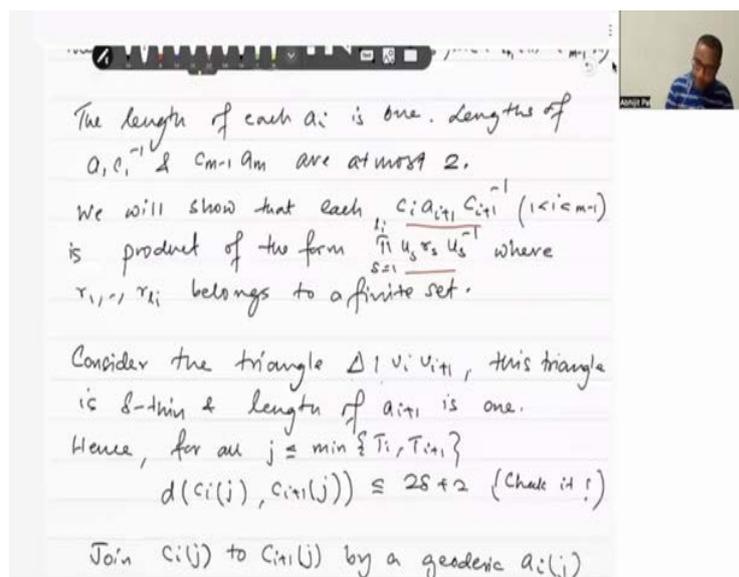
Next, define $c_1 = a_1$, $c_{m-1} = a_m$, and $c_m = 1$. Now, notice that the word w can be expressed as:

$$w = a_1 c_1^{-1} c_1 a_2 c_2^{-1} c_2 a_3 c_3^{-1} \cdots c_i a_{i+1} c_{i+1}^{-1} \cdots c_{m-1} a_m$$

What have we done here? We started with this loop, w , and we deconstructed it into a product of smaller sub-loops. Each sub-loop follows the pattern: proceed along c_{i-1} , then traverse via a_i , and return along c_i . Essentially, w is the product of these smaller loops.

There are some minor variations at the beginning and end of the word. At the starting point, the loop begins as $a_1 c_1^{-1}$, and at the end, it closes with $c_{m-1} a_m$. This gives us a clear representation of how the loop w is constructed and decomposed into smaller geodesic segments within the Cayley graph.

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Now, let's analyze the length of each a_i . Since the length of each a_i is 1, we can observe that the total length of the loops $a_1 c_1^{-1}$ and $c_{m-1} a_m$ will be at most 2. This is because c_1 corresponds to a_1 and c_{m-1} corresponds to a_m , leading to the conclusion that their combined length cannot exceed 2.

Next, we aim to demonstrate that each of these loops can be expressed as products of the form $u_s r_s u_s^{-1}$. Here, u_s and r_s belong to finite sets, meaning that r_1, r_2, \dots, r_l belong to a finite collection. If we can establish this relationship, then the word w can be represented as a product of finitely many conjugates. Consequently, this means that the loop will be finitely presented.

Our next goal is to prove that each of these sub-loops can indeed be expressed as a finite product of these conjugates. To do this, we will examine the triangle formed by the points 1 , T_i , and T_{i+1} .

(Refer Slide Time: 17:34)

Let the edge labeled by a_i have vertices v_i & v_{i+1} . Let c_i be a geodesic joining 1 (identity) and v_i . Let $c_i(j)$ be vertices on c_i s.t $d(c_i(j-1), c_i(j)) = 1$ where $j = 0, 1, \dots, T_i$

Now, let's take a closer look at this triangle; this is the triangle we will be focusing on this time.

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We will show that each $c_i a_{i+1} c_{i+1}^{-1}$ ($1 < i < m$) is product of the form $\prod_{s=1}^k u_s r_s u_s^{-1}$ where r_1, \dots, r_k belongs to a finite set.

Consider the triangle $\Delta(1, v_i, v_{i+1})$, this triangle is δ -thin & length of a_{i+1} is one.

Hence, for all $j \in \min\{T_i, T_{i+1}\}$

$$d(c_i(j), c_{i+1}(j)) \leq 2\delta + 2 \text{ (Check it!)}$$

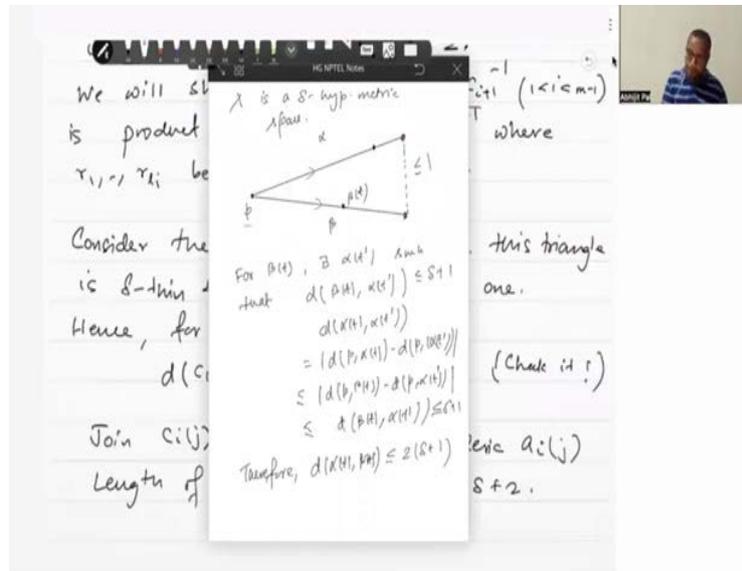
Join $c_i(j)$ to $c_{i+1}(j)$ by a geodesic $a_i(j)$

Length of $a_i(j)$ is at most $2\delta + 2$.

This triangle is denoted as Δ_n , and the length of a_{i+1} is equal to 1. Now, let's discuss T_i ; T_i represents the length of the geodesic c_i , while T_{i+1} corresponds to the length of the geodesic a_{i+1} .

It can be established that for $j \leq \min(T_i, T_{i+1})$, the distance between the points c_{ij} and c_{i+1j} is at most $2\delta + 2$. This conclusion follows from the observations we've made.

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Let us begin with the concept of a δ -hyperbolic metric space. We'll denote our space as X and consider two geodesics, α and β , which have endpoints that are at most a distance of 1 apart. Both geodesics, α and β , originate from the same point P .

Now, if we take a point β_t along the geodesic β , there exists a point along α such that the distance between β_t and this point on α is less than or equal to δ . Assuming this point is indeed on α , the distance from β_t to the endpoint of α will be at most $\delta + 1$. Consequently, we can find some t' such that the distance between $\alpha_{t'}$ and β_t is also at most $\delta + 1$.

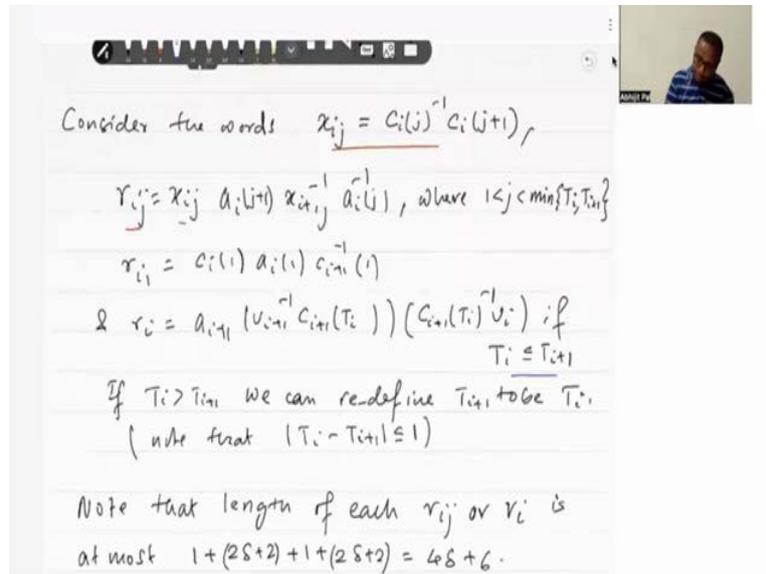
Applying the triangle inequality, we can then show that the distance between α_t and $\alpha_{t'}$ will be at most $\delta + 1$. Furthermore, if we take t for α_t and t' for β_t , we can deduce that the distance between α_t and β_t is less than or equal to $2\delta + 1$.

Using this information, we can establish that the distance between the points c_{ij} and c_{i+1j} is less than or equal to $2\delta + 1$. As previously mentioned, we can join c_{ij} and c_{i+1j} with the geodesic a_{ij} . This geodesic, labeled a_{ij} , will have a length of at most $2\delta + 2$.

Now, let us consider the words x_{ij} , which are defined as $x_{ij} = c_{ij}^{-1}c_{i(j+1)}$. Next, we define r_{ij} as follows:

$$r_{ij} = x_{ij} \cdot a_{i(j+1)} \cdot x_{(i+1)j}^{-1} \cdot a_{ij}^{-1}.$$

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To visualize this, let's refer back to our diagram. The geodesic labeled a_{ij} starts from a specific point, followed by traveling along x_{ij} . What does r_{ij} represent? Essentially, it begins at this point, traverses along x_{ij} , continues along $a_{i(j+1)}$, then follows the geodesic, and finally returns via a_{ij}^{-1} . Thus, r_{ij} describes a loop characterized by:

$$r_{ij} = x_{ij} \cdot a_{i(j+1)} \cdot x_{(i+1)j}^{-1} \cdot a_{ij}^{-1},$$

where j is constrained between 1 and the minimum of T_i and T_{i+1} . For the case of r_{i1} , we find it simplifies to the expression for $c_{i1} \cdot a_{i1} \cdot c_{(i+1)1}^{-1}$.

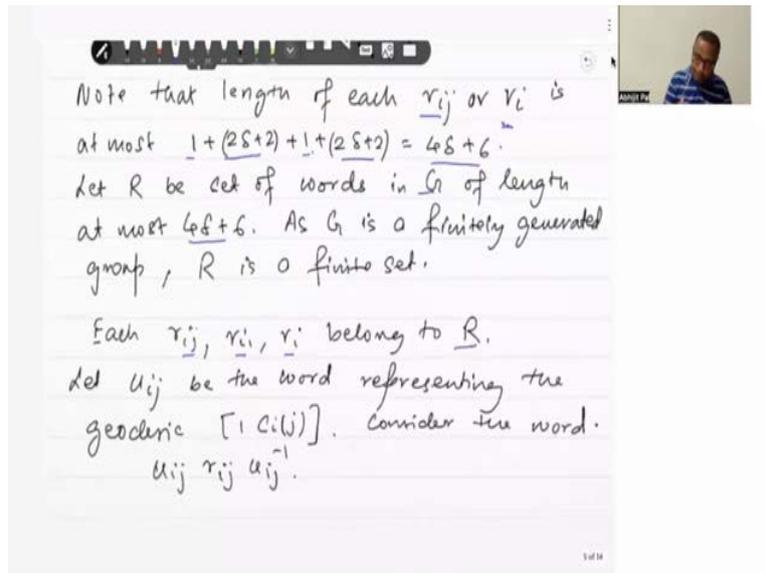
Now, let's consider the expression for r_i :

$$r_i = a_{i+1} \cdot T_{i+1}^{-1} \cdot c_{(i+1)} \cdot T_i,$$

multiplied by $c_{(i+1)} \cdot T_i^{-1} \cdot T_i$. This holds true under the condition that T_i is less than or equal to T_{i+1} .

Now, let us note that the length of each r_{ij} or r_i is bounded by the expression $1 + 2\delta + 2 + 1 + 2\delta + 2$. To analyze this further, let's refer to our diagram for r_{ij} . The length of x_{ij} is equal to 1, while the length of the geodesic $a_{i(j+1)}$ is at most $\delta + 2$. The length of the geodesic c_{ij} is exactly equal to 1, and similarly, the length of the geodesic a_{ij} is also at most $\delta + 2$.

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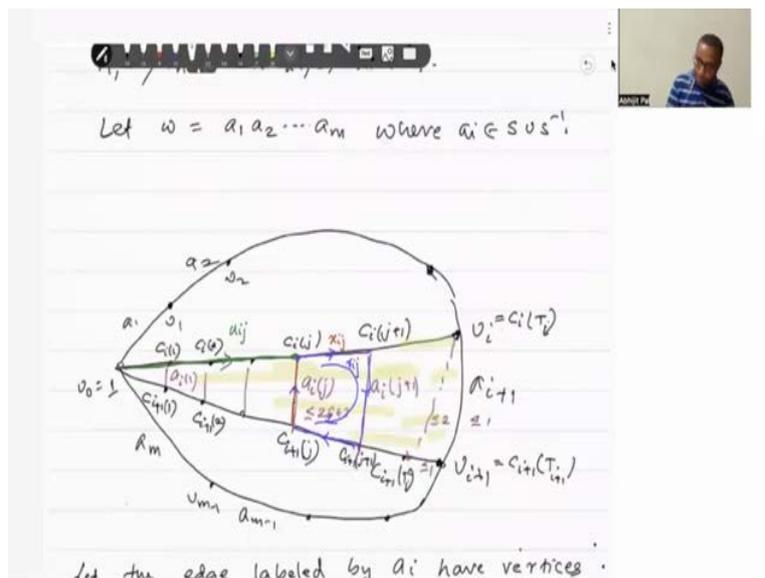


Putting all of this together, we can conclude that the length of r_{ij} is at most:

$$4\delta + 6.$$

By applying a similar reasoning, we find that the length of r_i , which appears at the end, will also be at most $4\delta + 6$.

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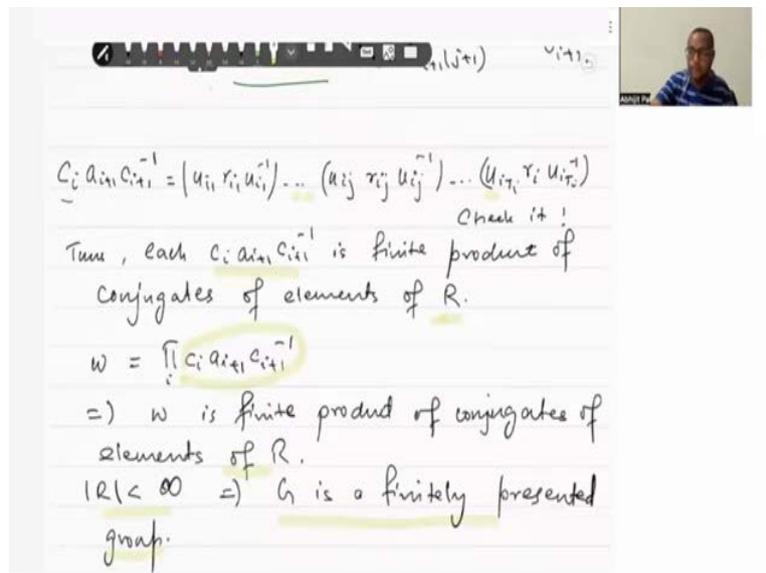


Now, let us define R as the set of words in G that have a length of at most $4\delta + 6$. Since the group G is finitely generated, it follows that R is a finite set. Furthermore, each of the elements

This sequence illustrates the journey: first, we travel along u_{ij} , then follow the loop r_{ij} , and finally, we conclude the path by returning back through u_{ij}^{-1} .

Now, we have this illustration in front of us. You can verify that the loop $c_i a_{i+1} c_i^{-1}$ is indeed the product of these smaller loops: $u_{i1} r_{i1} u_{i1}^{-1}, \dots, u_{ij} r_{ij} u_{ij}^{-1}$, and finally, $u_{i-1} r_{i-1} u_{i-1}^{-1}$. Importantly, each of these u terms represents a finite product of conjugates of elements from the set R , where r_{i1}, r_{ij} , and r_i all belong to this finite set R .

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Thus, we see that w is indeed the product of the loops $c_i a_{i+1} c_i^{-1}$, and each of these components is a finite product of conjugates. Consequently, we can conclude that w is a finite product of conjugates of elements from the set R . Since R is a finite set, we have successfully demonstrated that the group G is a finitely presented group. With that, I will conclude this discussion.