

# Calculus of Variations and Integral Equation

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Lecture No. # 35

Module No. # 01

Welcome viewers to the lecture series on Integral Equation under NPTEL courses. In last lecture, we have considered the Fredholm integral equation of second kind, with non homogenous term and we have discussed in case of separable or degenerate kernel, how the given Fredholm integral equation can be converted into a system of linear equation. And briefly we have discussed that, depending upon the existence of the solution of the system of the linear equation, we can find out solution to the given Fredholm integral equation.

In this lecture, first we considered one more example because, example we discussed in the type, because summation  $p_r(x), q_r(x), d_s$  for the selected problem contains only one term that is  $p_1$  and  $q_1$  term.

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Ex: 
$$y(x) = x + \lambda \int_{-\pi}^{\pi} (x \cos s + s^2 \sin x + \cos x \sin s) y(s) ds$$

$$p_1(x) = x, \quad p_2(x) = \sin x, \quad p_3(x) = \cos x$$

$$q_1(s) = \cos s, \quad q_2(s) = s^2, \quad q_3(s) = \sin s$$

$$K(x, s) = \sum_{r=1}^3 p_r(x) q_r(s)$$

$$y(x) = x + \lambda x \int_{-\pi}^{\pi} \cos s y(s) ds + \lambda \sin x \int_{-\pi}^{\pi} s^2 y(s) ds + \lambda \cos x \int_{-\pi}^{\pi} \sin s y(s) ds$$

$$= x + \lambda x y_1 + \lambda \sin x y_2$$

So, in this lecture we can start with this example, that we have to solve this equation,  $y(x)$  is equal to  $x$  plus  $\lambda$  integral minus  $\pi$  to plus  $\pi$   $x \cos s y(s) ds$  plus  $\lambda$  integral minus  $\pi$  to plus  $\pi$   $x^2 y(s) ds$  plus  $\lambda$  integral minus  $\pi$  to plus  $\pi$   $\sin s y(s) ds$ .

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$$y_1 = \int_{-\pi}^{\pi} \cos s y(s) ds, \quad y_2 = \int_{-\pi}^{\pi} s^2 y(s) ds, \quad y_3 = \int_{-\pi}^{\pi} \sin s y(s) ds$$

$$y(x) = x + \lambda y_1 x + \lambda y_2 \sin x + \lambda y_3 \cos x$$

$$y_1 = \int_{-\pi}^{\pi} [x \cos s + \lambda y_1 x \cos s + \lambda y_2 \sin s \cos s + \lambda y_3 \cos^2 s] ds$$

$$= (1 + \lambda y_1) \int_{-\pi}^{\pi} x \cos s ds + \lambda y_2 \int_{-\pi}^{\pi} \sin s \cos s ds + \lambda y_3 \int_{-\pi}^{\pi} \cos^2 s ds$$

$$= \lambda y_3 \int_0^{\pi} (1 + \cos 2s) ds = \lambda y_3 \left[ s + \frac{\sin 2s}{2} \right]_0^{\pi}$$

$$= \lambda y_3 \pi$$

So, with the notation we had discussed, in the last lecture, here  $p_1 x$  is equal to  $x$ ,  $p_2 x$ , this is equal to  $\sin x$ ,  $p_3 x$ , this is equal to  $\cos x$  and  $q_1 s$  this is equal to  $\cos s$ ,  $q_2 s$  this is equal to  $s^2$ ,  $q_3 s$  this is equal to  $\sin s$  and therefore kernel, given kernel  $k(x, s)$  is nothing but,  $\sigma_r$  running's from 1 to 3  $p_r x q_r s$ ; so now, we can write the integral equation into this format that is,  $y(x)$  equal to  $x$  plus  $\lambda$  integral minus  $\pi$  to plus  $\pi$   $x \cos s y(s) ds$  plus  $\lambda$  integral minus  $\pi$  to plus  $\pi$   $x^2 y(s) ds$  plus  $\lambda$  integral minus  $\pi$  to plus  $\pi$   $\sin s y(s) ds$  and that is equal to  $x$  plus  $\lambda y_1 x$  plus  $\lambda y_2 \sin x$  plus  $\lambda y_3 \cos x$ ; where this  $y_1$  stands for  $\int_{-\pi}^{\pi} x \cos s y(s) ds$ ,  $y_2$  this is equal to  $\int_{-\pi}^{\pi} x^2 y(s) ds$  and  $y_3$  this is equal to  $\int_{-\pi}^{\pi} \sin s y(s) ds$ .

So, as we have discuss in the last lecture that, now we have to multiple this expression that  $y(x)$  equal to  $x$  plus  $\lambda y_1 x$  plus  $\lambda y_2 \sin x$  plus  $\lambda y_3 \cos x$  by  $\cos x$ ,  $x^2$  and  $\sin x$  respectably and then we have to integrate from minus  $\pi$  to plus  $\pi$  in order to constitute the system of linear equation for  $y_1, y_2, y_3$ , so we can do that, alternatively we can think about that  $y(x)$ , this is equal  $x$  plus  $\lambda y_1 x$  plus  $\lambda y_2 \sin x$  plus  $\lambda y_3 \cos x$  and with these definition for  $y(s)$  we can

substitute this  $y_s$  into the definition for  $y_1, y_2, y_3$ , in order to construct the system of linear equations. So, therefore, from the definition for  $y_1$  we can write  $y_1$  equal to  $\int_{-\phi}^{\phi} \cos s \, ds$ .

Plus  $\lambda y_1 \int_{-\phi}^{\phi} \sin s \cos s \, ds$  plus  $\lambda y_2 \int_{-\phi}^{\phi} \sin s \cos s \, ds$  plus  $\lambda y_3 \int_{-\phi}^{\phi} \cos^2 s \, ds$  and from here, we can write this is equal to  $1 + \lambda y_1 \int_{-\phi}^{\phi} \sin s \cos s \, ds$  plus  $\lambda y_2 \int_{-\phi}^{\phi} \sin s \cos s \, ds$  plus  $\lambda y_3 \int_{-\phi}^{\phi} \cos^2 s \, ds$ ; now past two integrals initiates as  $\sin s \cos s$  is a odd function,  $\sin s \cos s$  is also an odd function and in both the cases in limit is from  $-\phi$  to  $\phi$ , so both of them is equal to 0 and the last integral can be written as  $\lambda y_3 \int_0^{\phi} (1 + \cos 2s) \, ds$ , because  $-\phi$  to  $\phi$  can be converted into  $0$  to  $\phi$  and then  $2 \cos^2 s$  is nothing but,  $1 + \cos 2s$  and after integration will be having  $\lambda y_3 (s + \frac{\sin 2s}{2})$  limit from  $0$  to  $\phi$  and therefore, this will results in this is equal to  $\lambda y_3 \phi$  this will be the result for the first part.

And then for the second expression  $y_2$ , this is equal to  $\int_{-\phi}^{\phi} y_s^2 \, ds$  and this is equal to  $\int_{-\phi}^{\phi} y_s^2 \, ds$ , substituting the expression for the  $y_s$ , we can find this is  $s^3 + \lambda y_1 s^3 + \lambda y_2 s^2 \sin s + \lambda y_3 s^2 \cos s \, ds$  and again here,  $s^3 + \lambda y_1 s^3$  this will be 0, because this is hot function and  $s^2 \sin s$  is also a odd function.

So therefore, we are left with the last integral, that is  $\int_{-\phi}^{\phi} \lambda y_3 s^2 \cos s \, ds$  and this will be equal to  $2 \lambda y_3 \int_0^{\phi} s^2 \cos s \, ds$  and after integrating by parts, we find  $2 \lambda y_3 (s^2 \sin s + 2s \cos s - 2 \sin s)$  limit  $0$  to  $\phi$  and ultimately we will having only one nonzero term, that is from  $2s \cos s$  when evaluated at  $s$  equal to  $\phi$ .

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The image shows a handwritten derivation on a whiteboard. It starts with the equation  $y_2 = \int_{-\pi}^{\pi} s^2 y(s) ds$ . This is then expanded into  $\int_{-\pi}^{\pi} [s^3 + \lambda y_1 s^3 + \lambda y_2 s^2 \sin s + \lambda y_3 s^2 \cos s] ds$ . The integral is split into two parts:  $\int_{-\pi}^{\pi} \lambda y_3 s^2 \cos s ds = 2\lambda y_3 \int_0^{\pi} s^2 \cos s ds$  and  $\int_{-\pi}^{\pi} [s^3 + \lambda y_1 s^3 + \lambda y_2 s^2 \sin s] ds = 2\lambda y_3 [s^2 \sin s + 2s \cos s - 2 \sin s]_0^{\pi}$ .

So, substituting this limit, **Upper** lower limits and upper limits this will results in minus 4 lambda phi y 3 and finally for y 3, this is equal to integral minus phi to plus phi, you can recall the definition, this is minus phi to plus phi sin s y s d s.

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The image shows a handwritten derivation on a whiteboard. It starts with the equations  $y_1 = \int_{-\pi}^{\pi} \cos s y(s) ds$ ,  $y_2 = \int_{-\pi}^{\pi} s^2 y(s) ds$ , and  $y_3 = \int_{-\pi}^{\pi} \sin s y(s) ds$ . Then,  $y(s) = s + \lambda y_1 s + \lambda y_2 \sin s + \lambda y_3 \cos s$  is substituted into the integral for  $y_1$ :  $y_1 = \int_{-\pi}^{\pi} [s \cos s + \lambda y_1 s \cos s + \lambda y_2 \sin s \cos s + \lambda y_3 \cos^2 s] ds$ . This is simplified to  $(1 + \lambda y_1) \int_{-\pi}^{\pi} s \cos s ds + \lambda y_2 \int_{-\pi}^{\pi} \sin s \cos s ds + \lambda y_3 \int_{-\pi}^{\pi} \cos^2 s ds$ . The final result is  $2\lambda y_3 \pi$ .

So, this is sin s y s d s and substituting the expression for y s, this reduces to minus phi to plus phi, s sin s plus lambda y 1 s sin s plus lambda y 2 sin square s plus lambda y 3 sin s cosine s d s.

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$$\begin{aligned}
 y_1 - \lambda\pi y_3 &= 0 \\
 y_2 + 4\lambda\pi y_3 &= 0 \\
 -2\lambda\pi y_1 - \lambda\pi y_2 + y_3 &= 2\pi
 \end{aligned}$$

$$\begin{bmatrix} 1 & 0 & -\lambda\pi \\ 0 & 1 & 4\lambda\pi \\ -2\lambda\pi & -\lambda\pi & 1 \end{bmatrix} \quad \begin{vmatrix} 1 & 0 & -\lambda\pi \\ 0 & 1 & 4\lambda\pi \\ -2\lambda\pi & -\lambda\pi & 1 \end{vmatrix} = 1 + 2\lambda^2\pi^2$$

$$y_1 = \lambda\pi y_3, \quad y_2 = -4\lambda\pi y_3$$

$$y_3 = \frac{2\pi}{1 + 2\lambda^2\pi^2}, \quad y_1 = \frac{2\pi^2\lambda}{1 + 2\lambda^2\pi^2}$$

$$y_2 = \frac{-8\pi^2\lambda}{1 + 2\lambda^2\pi^2}$$

And this will be equal to 2 into 1 plus lambda y 1 integral 0 to phi s sin s d s, because s sin is a even function and from limit is to minus phi to plus phi, then plus 2 lambda y 2 integral 0 to phi sin square s d s and last integral is again equal to 0 because sin s cosine s an odd function and after evaluating this integral, we can find 2 into 1 plus lambda y 1, then limit minus s cosine s plus sin s 0 to phi plus lambda y 2 s minus sin 2 s divided by 2 limit 0 to phi and this will results in 2 phi plus 2 lambda phi y 1 plus lambda phi y 2, this is the result.

So now, if we collect all the equation that we obtain, so from first we have obtain y 1 equal to lambda phi y 3, then y 2 equal to minus 4 lambda phi y 3 and finally, here y 3 equal to 2 phi plus 2 lambda phi y 1 plus lambda phi y 2, so finally we can write down the system of equation as y 1 minus lambda phi y 3 this is equal to 0, then y 2 plus 4 lambda phi y 3 this is equal to 0 and minus 2 lambda phi y 1 minus lambda phi y 2 plus y 3, this is equal to 2 phi.

So, therefore, the co-efficient matrix is consisting of this coefficients, that is 1, 0, minus lambda phi, then 0, 1, 4 lambda phi and minus 2 lambda phi minus lambda phi 1. So, therefore, we have unique solution if this determinant is non-zero; now, if we calculate this determinant, that is determinant 1 0 minus lambda phi, 0, 1, 4 lambda phi minus 2 lambda phi, then minus lambda phi 1, this determinant will be equal to 1 plus 2 lambda square phi square.

So, just for example, if we assume lambda is real; so, therefore, we can say this quantity is always not equal to 0 and therefore, for all values of lambda, this system of equation is uniquely solvable. Now, without going towards the matrix inversion method or Cramer's rule to solve this system of linear equation, directly from this equation you can find y 1, that is equal to lambda phi y 3 and y 2 this is equal to minus 4 lambda phi y 3 and substituting this two expressions in the third equation, we can then solve for y 3 and solving we get, y 3 equal to 2 phi divided by 1 plus 2 lambda square phi square.

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$$y(x) = x + \frac{2\lambda\pi}{1+2\lambda^2\pi^2} (\lambda\pi x - 4\lambda\pi \sin x + \cos x)$$

$$y(x) = f(x) + \lambda \int_a^b k(x,s) y(s) ds$$

$$k(x,s) = \sum_{r=1}^n p_r(x) q_r(s)$$

$$(I_n - \lambda A_n(x)) Y = B$$

$$B = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{bmatrix}$$

So, with this y 3, immediately we can find y 1, this is equal 2 phi square lambda divided by 1 plus 2 lambda square phi square and y 2 this is equal to minus 8 phi square lambda divided by 1 plus 2 lambda square phi square and therefore, with these expression for y 1 y 2 and y 3, we can find the solution for the given problem that is, y x is equal to x plus 2 lambda phi divided by 1 plus 2 lambda square phi square, this multiplied with lambda phi x minus 4 lambda phi sin x plus cosine x, so this is the solution. That means, we actually, we are substituting these expression for y 1, y 2, y 3 into the first expression, where we have obtain y x is equal to x plus lambda x y 1 plus lambda sin x y 2 plus lambda cosine x y 3, so substituting this values, we can get the general solution.

Now we discuss, different possible situation for the solution of the system linear equation what we have derive in the last lecture, and through which we can understand what is the concept of Eigen values, Eigen functions associated with a linear integral

equation that is Fredholm integral equations. So, for that purpose we recall that, the given integral equation  $y(x)$  is equal to  $f(x)$  plus  $\lambda$  integral  $a$  to  $b$   $k(x, s) y(s) ds$ , where  $k(x, s)$  is the degenerate or separable kernel, which is of the form  $\sum_{r=1}^n p_r(x) q_r(s)$  can be converted into a system of linear equations which is given by  $(I_n - \lambda A_{n \times n}) y$ , that is equal to  $\beta$ . So that means, existence of solution of the system of the linear equation, where  $y$  is the unknown, column vector with  $n$  components  $y_1, y_2, y_3$  up to  $y_n$ ; we can discuss the different possible situations, for the solution of the Fredholm integral equation.

So first of all, you can recall this  $\beta$  was a matrix of the form, some constant  $\beta_1, \beta_2$  up to  $\beta_n$  and this  $\beta_1, \beta_2$  up to  $\beta_n$  these are nothing but, the integral  $a$  to  $b$   $f(x) q_r(x) dx$ , so therefore, if we assume the first case if we assume that,  $f(x)$  equal to 0, if we assume  $f(x)$  equal to 0, then all the  $\beta_j$  are identically equal to 0 and therefore, these  $\beta$  is nothing but and  $n \times 1$  column vector and once  $n \times 1$  column vector is  $\beta$  and therefore, we will be having the system of linear homogenous equation  $(I_n - \lambda A_{n \times n}) y$ , that is equal to  $\theta_{n \times 1}$  and whenever  $f(x)$  equal to 0.

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$f(x) = 0, \quad \beta = \theta_{n \times 1}$   
 $(I_n - \lambda A_{n \times n}) y = \theta_{n \times 1}$   
 $y = \theta_{n \times 1} \quad y_1 = y_2 = \dots = y_n = 0$   
 $y(x) = 0$   
 $|I_n - \lambda A_{n \times n}| \neq 0, \quad y = \theta_{n \times 1}$   
 $y(x) = 0$  is the only sol<sup>n</sup> for  $y(x) = \int_a^b k(x,s) y(s) ds$ .  
 $|I_n - \lambda A_{n \times n}| = 0$

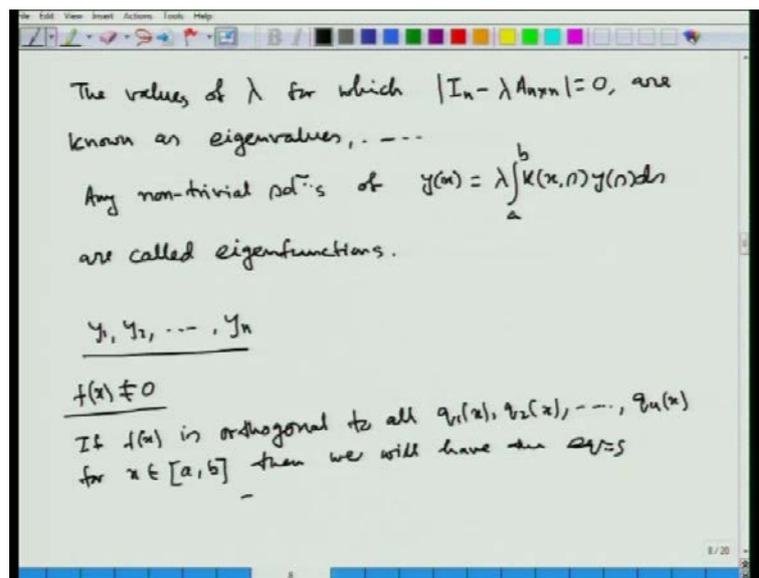
Then, the given Fredholm integral equation of second kind is a homogenous Fredholm integral equation of the second kind and therefore, this system of equation admit solutions  $y$  is equal to  $\theta_{n \times 1}$ , this is the trivial solution and whenever  $y_1, y_2$ , up to  $y_n$  all these quantities are identically equal to 0. So therefore,  $y(x)$  equal to 0 is a

solution to the given Fredholm integral equation which is a homogenous equation, because  $f(x) = 0$ .

Now, if it happens that  $|I_n - \lambda A_{n \times n}| \neq 0$ , this is not equal to zero, then unique solution for this homogenous system of linear equation is  $y = 0$  and therefore, from here you can verify, that  $y = 0$  **is the only solution** is the only solution for this integral equation  $y(x) = \int_a^b k(x, n) y(n) ds$ . So, this is the unique solution and which is identically equal to 0; so, therefore, this homogenous Fredholm integral equation admits only the previous solution.

Next, we considered case that,  $|I_n - \lambda A_{n \times n}| = 0$ , now what is happening here, if this is equal to 0, then at least one of the  $y_j$  can be assigned some arbitrary nonzero, if this determinant is 0, then we can assign at least one of the  $y_j$  arbitrary nonzero quantity and then accordingly, remaining  $y_j$  can be obtain in terms of this  $y_j$  and this choice of arbitrary values for  $y_j$  as it is arbitrary. So, therefore, it actually admits infinitely many solutions of the integral equation, so this is very much important point, if this determinant  $|I_n - \lambda A_{n \times n}| = 0$ , then we have infinitely many solutions of the integral equations.

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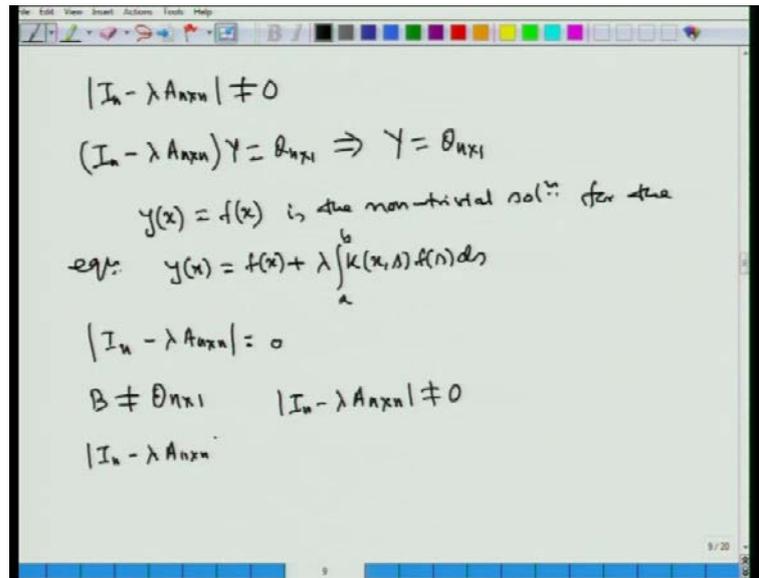
Now, the value of lambda **the value of lambda** for which this determinant is 0, the value of lambda for which this determinant  $|I_n - \lambda A_{n \times n}| = 0$ ,

these are known as **known as** characteristic values or Eigen values, Eigen values of the Fredholm integral equation. And any nontrivial solution **any nontrivial solution** of the homogenous integral equation associate with the  $i$  n  $\lambda$ , those are actually called the Eigen function; so therefore, any nontrivial solution **any non trivial solution** of  $y(x)$  is equal to  $\lambda \int_a^b k(x, s) y(s) ds$  are called Eigen functions. So, this is the definition or concept associate with the Eigen value and Eigen function of an integral equation.

Now, the point is that if the aim of the constants; that means, among these  $y_1, y_2$  up to  $y_n$  among these, if  $m$  can be assigned to arbitrary values for a given particular value of  $\lambda$ , then we can find  $m$  linearly independent, Eigen functions that can be obtain; so that means, depending upon the how many of this  $y_1, y_2$  up to  $y_n$  can be assigned as arbitrary constant, then in the solution those  $p_1(x), p_2(x)$  up to  $p_n(x)$  they will be appear and those will be actually Eigen functions corresponding to this arbitrary choice of  $y_1, y_2$  up to  $y_n$  for which this  $y_j$  are actually non-zero, of course will explain this idea with help of a particular example. So, up to this we have considered  $f(x) = 0$ , next we considered that,  $f(x)$  this is not equal to 0, if  $f(x)$  not equal to 0 still there is possibility, that we can have system of linear homogenous equations corresponding to that,  $(i - \lambda) a_n \times n y$  is equal to  $b$ .

And the point is that, if  $f(x)$  is orthogonal **is orthogonal** to all  $q_1(x), q_2(x)$  up to  $q_n(x)$ , for  $x$  belongs to close interval  $a, b$ , then we will have the equation that is,  $(i - \lambda) a_n \times n$  multiplied by  $y$ , that is equal to  $\theta_n \times 1$ ; so, therefore, as we have discuss earlier, there will be two possibilities, number 1 that determinate of  $(i - \lambda) a_n \times n$ , this is not equal to 0.

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Now, if this is not equal to 0, then the system of linear equation in  $n$  minus  $\lambda$   $a$   $n$  cross  $n$  times  $y$ , that is equal to  $\theta$   $n$  cross  $1$  admits only one solution, that is  $y$  equal to  $\theta$   $n$  cross  $1$ ; but in these case, will be having a non trivial solution, that is given by  $y$   $x$  is equal to  $f$   $x$ , so  $y$   $x$  equal to  $f$   $x$  is the non trivial solution **is the non tribunal solution** for the equation  $y$   $x$  is equal to  $f$   $x$  plus  $\lambda$  integral  $a$  to  $b$   $k$  of  $x$  comma  $s$   $f$   $s$   $d$   $s$ .

And the case when will be having this  $i$   $n$  minus  $\lambda$   $a$   $n$  cross  $n$  this determinant equal to 0, then we can find the corresponding Eigen values and therefore, will be having Eigen functions and in that case, solution will be the some of  $f$   $x$  and the stiller multiple of Eigen functions of the associated problem. And finally, if we considered that, at least 1 of integral  $a$  to  $b$   $f$   $x$   $q$   $m$   $x$  is nonzero, so that means, we are assuming  $B$  not equal to  $\theta$   $n$  cross  $1$  if this happens, then will be having unique solution to the Fredholm integral equation whenever determinant of  $i$   $n$  minus  $\lambda$   $a$   $n$  cross  $n$  this is not equal to 0.

So, therefore, for  $b$  not equal to  $\theta$   $n$  cross  $1$  will be having unique solution to the Fredholm integral equation, if this determinant does not initiates and in case, if this happen that  $i$   $n$  minus  $\lambda$   $a$   $n$  cross  $n$  this is equal to 0, then system of equation will be either income system and if the system of the equations are income system, they does not exist any solution are they are redundant; in case of redundant equation will be having infinitely many solutions for the given problem.

So, this is all about discussion regarding nature of solution of the Fredholm integral equation associate with the nature of the determinate  $i \ n \ minus \ lambda \ a \ n \ cross \ n$  and with that the matrix  $b$  is a no matrix or it is a non **non** matrix.

Now, in the last lecture we obtain the resolvent kernel of a integral equation, in these case we are again going to address the same problem and based upon this discussion, we can find out the Eigen values, Eigen functions and we will be able to illustrate all these ideas with help of the same example.

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Ex.  $y(x) = f(x) + \lambda \int_0^1 (1-3xs)y(s) ds$

$$= f(x) + \lambda \int_0^1 y(s) ds - 3\lambda x \int_0^1 s y(s) ds$$

$$y_1 = \int_0^1 y(s) ds, \quad y_2 = \int_0^1 s y(s) ds$$

$$y(x) = f(x) + \lambda y_1 - 3\lambda x y_2$$

$$y_1 = \int_0^1 y(s) ds = \int_0^1 f(s) ds + \lambda y_1 - 3\lambda y_2 \int_0^1 s ds$$

$$= \int_0^1 f(s) ds + \lambda y_1 - \frac{3}{2} \lambda y_2$$

$$\Rightarrow (1-\lambda) y_1 + \frac{3}{2} \lambda y_2$$

So, the problem is  $y \ x$  **y x** this is equal to  $f \ x$  plus  $\lambda$  integral 0 to 1,  $1 \ minus \ 3 \ x \ s \ y \ s \ d \ s$  and just for your information you can get this example in the Hildebrand's book on mathematical method or any other book like was **was** book or carnivals book this very famous example, you can find it in several places on the book of integral equations.

So now, we are going to discuss the solution of the particular problem depending upon various natures of  $f \ x$  that is whether it is 0 or it is non-zero or whenever its orthogonal to the function associated with the given problem, so, first of all we can derived this equation as  $f \ x$  plus  $\lambda$  integral 0 to 1  $y \ s \ d \ s$  minus  $3 \ lambda \ x$  integral 0 to 1  $s \ y \ s \ d \ s$  and defining  $y \ 1$  is equal to integral 0 to 1  $y \ s \ d \ s$  and  $y \ 2$  is equal to integral 0 to 1  $s \ y \ s \ d \ s$ , we can write  $y \ x$ , this is equal to  $f \ x$  plus  $\lambda \ y \ 1$  minus  $3 \ lambda \ x \ y \ 2$ , so this is the expression for  $y \ x$ .

Now, in this expression, that is  $y_1$  is equal to  $\int_0^1 y_2 ds$  substituting this expression for  $y_2$ , we can find this is equal to  $\int_0^1 f(s) ds + \lambda y_1 - \lambda y_2$   $\int_0^1 ds$  minus  $3\lambda y_2 \int_0^1 ds$ , so this will be equal to  $\int_0^1 f(s) ds + \lambda y_1 - 3\lambda y_2$  and therefore, from here we have the first equation of the system of two linear equations, that is  $1 - \lambda y_1 + 3\lambda y_2$  that is equal to  $\int_0^1 f(s) ds$ , so this is the first equation.

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$$y_2 = \int_0^1 s y_2(s) ds = \int_0^1 s f(s) ds + \frac{\lambda}{2} y_1 - \lambda y_2$$

$$\Rightarrow -\frac{\lambda}{2} y_1 + (1+\lambda) y_2 = \int_0^1 s f(s) ds$$

$$|I_2 - \lambda A_{2 \times 2}| = \begin{vmatrix} 1-\lambda & \frac{3}{2}\lambda \\ -\frac{\lambda}{2} & 1+\lambda \end{vmatrix} = \frac{1}{4}(4-\lambda^2)$$

$\lambda \neq \pm 2$

If  $f(x) = 0$ , then  $\lambda \neq \pm 2$ ,  $y(x) = 0$ .

And for the second  $y_2$  is equal to  $\int_0^1 s y_1 ds$  and after substituting the expression for  $y_1$  and evaluating the integral, you can find  $\int_0^1 s f(s) ds + \lambda y_2 y_1$  minus  $\lambda y_2$ , and from there we can write, minus  $\lambda y_2 y_1 + \lambda y_2$ , this is equal to  $\int_0^1 s f(s) ds$  and therefore the determinate, that is  $2 - \lambda$  cross  $2$  this is equal to determinate  $1 - \lambda$   $3\lambda y_2$ , then minus  $\lambda y_2$  and  $1 + \lambda$ , so, this is equal to after simplification will be comes out to be  $1 + 4$  **four** minus  $\lambda$  square.

So in this case we can say that, unique solution exists whenever  $\lambda$  not equal to plus minus 2, if  $\lambda$  not equal to plus minus 2, so whether  $f$  is equal to 0 or  $f$  is not equal to 0, we can find unique solution for the given Fredholm integral equation.

now and the solution can be obtain by substituting the expression for  $y_1$  and  $y_2$ , by solving these two equation either in the form involving  $\int_0^1 f(s) ds$  and  $\int_0^1 s f(s) ds$  and other wise if  $f(x)$  is given. So, evaluating both this integrals that is  $\int_0^1 f(s) ds$

and  $\int_0^1 f(x) dx$ , you can find out uniquely  $y_1$  and  $y_2$  and then substituting into required expression, that is  $y(x) = f(x) + \lambda y_1 - 3\lambda y_2$ , you can find out the unique solution for the given problem.

Now, we considered the case, that if  $f(x) = 0$  then, for  $\lambda \neq \pm 2$ ,  $y(x) = 0$  is the only solution. So, therefore, if  $f(x) = 0$  and  $\lambda \neq \pm 2$ , then given problem admits only trivial solution and now, we can consider the cases that is values of  $\lambda = 2$  and then  $\lambda = -2$ .

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The image shows a digital whiteboard with the following handwritten mathematical steps:

$$(1-\lambda)y_1 + \frac{3}{2}\lambda y_2 = \int_0^1 f(x) dx$$

$$-\frac{\lambda}{2}y_1 + (1+\lambda)y_2 = \int_0^1 x f(x) dx$$

For  $\lambda = 2$ ,  $f(x) \neq 0$

$$y_1 - 3y_2 = -\int_0^1 f(x) dx$$

$$y_1 - 3y_2 = -\int_0^1 x f(x) dx$$

$$\int_0^1 f(x) dx = \int_0^1 x f(x) dx \Rightarrow \int_0^1 (1-x)f(x) dx = 0$$

So, we have this system of equation you can recall, that  $(1-\lambda)y_1 + 3\lambda y_2 = \int_0^1 f(x) dx$  and  $-\frac{\lambda}{2}y_1 + (1+\lambda)y_2 = \int_0^1 x f(x) dx$ .

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$\lambda = -2, f(x) \neq 0$   
 $y_1 - y_2 = \frac{1}{3} \int_0^1 f(s) ds$   
 $y_1 - y_2 = \int_0^1 s f(s) ds$   
 $\int_0^1 (1-3s) f(s) ds = 0$   
 If  $f(x) = 0$   
 $\lambda \neq \pm 2$  then  $y(x) = 0$  is the only sol.  
 For  $\lambda = 2$  and  $f(x) = 0$ , we get,  
 $y_1 - 3y_2 = 0$

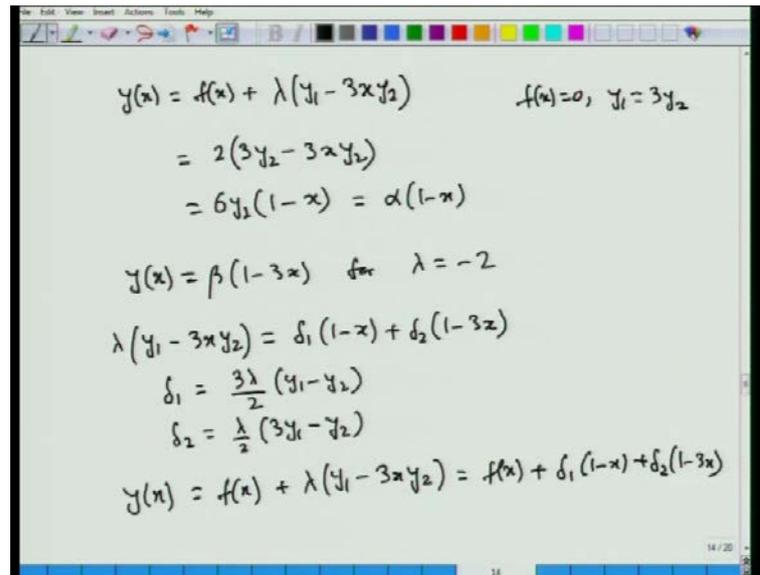
So, here if we assume that, lambda equal to 2 and f s not equal to 0 havoc system of equation reduces to  $y_1 - 3y_2 = \frac{1}{3} \int_0^1 f(s) ds$  and  $y_1 - 3y_2 = \int_0^1 s f(s) ds$ , that is equal to minus integral 0 to 1 f s d s and  $y_1 - 3y_2 = \int_0^1 s f(s) ds$ , so these are two expressions will be getting when we substituting lambda equal to 0 and with the assumption that f x is not equal to 0.

So, with f x not equal to 0 will be having this expression, now havoc two equations that is  $y_1 - 3y_2 = \frac{1}{3} \int_0^1 f(s) ds$  and  $y_1 - 3y_2 = \int_0^1 s f(s) ds$  these are in comfortable, unless  $\int_0^1 f(s) ds$ , this is equal to  $\int_0^1 s f(s) ds$ , so actually, that implies  $\int_0^1 (1-3s) f(s) ds = 0$ . So, if these condition does not holds, that is  $\int_0^1 (1-3s) f(s) ds \neq 0$ , then the system of equation are in comfortable and therefore, they does not exists any solution.

Similarly, for lambda equal to minus 2 and f x not equal to 0 will be having the system of equation reduce to  $y_1 - y_2 = \frac{1}{3} \int_0^1 f(s) ds$  and from the second  $y_1 - y_2 = \int_0^1 s f(s) ds$  and in this case the system of equation are in comfortable unless  $\int_0^1 (1-3s) f(s) ds = 0$  and these condition holds that is  $\int_0^1 (1-3s) f(s) ds = 0$ , then the system of equation actually redundant, because in these case both this equation can be reduce to a single equation.

So now, the case when  $f(x)$  is equal to 0 if  $f(x)$  equal to 0 and  $\lambda$  not equal to plus minus 2, then  $y(x)$  equal to 0 is the only solution, that we have discuss earlier also and next we can try to calculate the Eigen functions associate with the Eigen values, plus minus 2; whenever this  $f(x)$  equal to 0, now for  $\lambda$  equal to 2 and  $f(x)$  equal to 0 both this equation can be reduce to  $y_1 - 3y_2$  this is equal to 0.

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$$\begin{aligned}
 y(x) &= f(x) + \lambda(y_1 - 3xy_2) & f(x)=0, y_1=3y_2 \\
 &= 2(3y_2 - 3xy_2) \\
 &= 6y_2(1-x) = \alpha(1-x) \\
 y(x) &= \beta(1-3x) \quad \text{for } \lambda = -2 \\
 \lambda(y_1 - 3xy_2) &= \delta_1(1-x) + \delta_2(1-3x) \\
 \delta_1 &= \frac{3\lambda}{2}(y_1 - y_2) \\
 \delta_2 &= \frac{\lambda}{2}(3y_1 - y_2) \\
 y(x) &= f(x) + \lambda(y_1 - 3xy_2) = f(x) + \delta_1(1-x) + \delta_2(1-3x)
 \end{aligned}$$

And then from the expression, that is  $y(x)$  is equal to  $f(x)$  plus  $\lambda(y_1 - 3xy_2)$  with the substitution, that is  $f(x)$  equal to 0 and  $y_1$  equal to  $3y_2$ ; we can find this is equal to 2 times  $3y_2 - 3xy_2$ , so this is equal to  $6y_2(1-x)$ , now we can choose  $y_2$  arbitrary quantity and accordingly  $y_1$  will also be the arbitrary quantity and therefore  $6y_2$ .

Can be written as  $\alpha(1-x)$ , so therefore, this  $1-x$  actually Eigen function associate with Eigen value two of the homogenous Fredholm integral equation and proceeding in a similar manner. We can find that,  $y(x)$  is equal to  $\beta(1-3x)$  for  $\lambda$  equal to minus 2, where  $\beta$  is any arbitrary non-zero quantity and therefore, we can say that  $1-x$  and  $1-3x$ , these are Eigen function corresponding to Eigen values;  $\lambda$  equal to 2 and  $\lambda$  equal to minus 2 respectively.

And finally you can check that, this lambda times y 1 minus 3 x y 2, these can be written in terms of linear combination of these two functions, that is 1 minus x and 1 minus 3 x, because this can be done, that this is equal to delta 1 times 1 minus x plus delta 2 times 1 minus 3 x if we choose delta 1 equal to 3 lambda by 2 times y 1 minus y 2 and delta 2, this is equal to lambda by 2 3 y 1 minus y 2. So, from here you can see that, always this lambda times y 1 minus 3 x y 2 can be written as delta minus 1 minus x and delta 2 times 1 minus 3 x.

So this 1 minus x and 1 minus 3 x; they are Eigen functions of the associated problem and therefore the solution, that is y x this is equal to f x plus lambda into y 1 minus 3 x y 2 is nothing, but the some of this given function f x and linear combination of the Eigen functions, that is delta 1 into 1 minus x plus delta 2 into 1 minus 3 x. So that, we have claim in case during the theoretical discussion on this problem that, whenever this lambda is taking the value plus minus 2 and f x is non-zero.

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The image shows a whiteboard with handwritten mathematical derivations. The top part shows the case for  $\lambda = 2$ . It starts with the condition  $\int_0^1 (1-s)f(s)ds \neq 0$ . Then it defines  $y_1 = 3y_2 - \int_0^1 f(s)ds$ . The main equation is  $y(x) = f(x) + \lambda(y_1 - 3xy_2)$ . This is expanded to  $y(x) = f(x) + 2(3y_2 - \int_0^1 f(s)ds - 3xy_2)$ , which simplifies to  $y(x) = f(x) - 2\int_0^1 f(s)ds + \alpha(1-2)$ . The bottom part shows the case for  $\lambda = -2$ , with the condition  $\int_0^1 (1-3s)f(s)ds \neq 0$ , and concludes with "no sol<sup>n</sup> for the given".

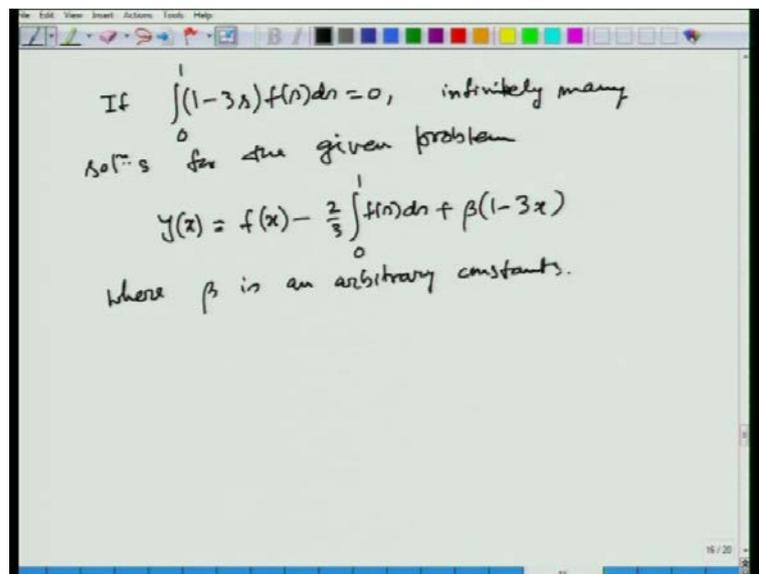
so therefore, the solution can be written as the linear combination of the Eigen functions for some with the given functions f x, for lambda equal to 2 no solution exists if  $\int_0^1 (1-s)f(s)ds \neq 0$ ; if this quantity is not equal to 0, that is the integral  $\int_0^1 (1-s)f(s)ds \neq 0$ , then they does not exists any solution and in case f s is orthogonal to 1 minus s within the range 0 to 1.

So that means,  $\int_0^1 (1-3s)f(s)ds = 0$  in that case, we can write  $y_1$  is equal to  $3y_2 - \int_0^1 f(s)ds$ , this is the result will come up for  $y_1$

And in that case, we can write down the solution of the given problem, that is  $y(x)$  equal to  $f(x) + \lambda y_1 - 3xy_2$  and substituting the expression for this  $y_1$ , we can write  $f(x) + 2 \int_0^1 f(s)ds - 3xy_2$  and ultimately, this is coming out the  $f(x) - 2 \int_0^1 f(s)ds + \alpha(1-x)$ , because  $6y_2 - 6xy_2$  can be clubbed into  $6y_2(1-x)$  and  $6y_2$ , this  $y_2$  is an arbitrary quantity in this case, for  $\lambda = 2$  then  $6y_2$  can be written as arbitrary quantity  $\alpha$  and hence, the solution is given by  $y(x)$  is equal to  $f(x) - 2 \int_0^1 f(s)ds + \alpha(1-x)$ .

And in that case **in this case** you can easily verify that any non-zero values of  $\alpha$  you can get an infinite set of solution for the given problem. For example, substituting  $\alpha$  equal to 1 2 3 4 and so on, in all the cases you will be having  $y(x)$  equal to  $f(x) - 2 \int_0^1 f(s)ds + \alpha(1-x)$  these are the solution of the given **(O)** equation, so in this case, we will be having infinite number of solutions and for  $\lambda = -2$ .

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And if these condition is satisfied that is  $\int_0^1 (1-3s)f(s)ds \neq 0$  then no solution for the given equation, then they does not exists any solution for the given equation and for  $\lambda = -2$ , we can again find the solution for the

given problem in a similar fashion; that means, if we find that  $\int_0^1 (1 - 3s) f(s) ds$  is equal to 0, then we can find infinitely **infinitely** many solutions for the given problem.

And in this case the solution can be obtained as  $y(x)$  is equal to  $f(x) - \frac{2}{3} \int_0^1 f(s) ds + \beta(1 - 3x)$ , where  $\beta$  is an arbitrary constant, so this clearly shows under different possibilities, that is whenever  $f(x)$  is identically equal to 0, then we will be having a system of linear homogeneous equations and depending upon values of  $\lambda$ , we can have either a unique solution or no solution and in case  $f(x)$  is not equal to 0 and the determinant, that is  $\det(A - \lambda I)$  is not equal to 0, we will be having the trivial solution that is  $y(x) = 0$  is the only solution.

And in case that the determinant is non-zero, then we will have infinitely many solutions and another point, that we have to keep in mind that only  $f(x) = 0$  will not be corresponding to the system of linear homogeneous equations that is  $\det(A - \lambda I) y = \theta$ , in case the non-homogeneous part of the given Fredholm integral equation  $f(x)$  satisfies the condition that it is orthogonal to each of the functions  $\phi_1(x), \phi_2(x), \dots, \phi_n(x)$ , within the interval  $[a, b]$ .

Then still we will be having a system of linear homogeneous equations and depending upon the nature of the determinant, whether this is equal to 0 or this is non-zero will be having the case of a unique solution or no solution and with these examples we have illustrated, that in some situations when Eigen values and Eigen functions exist for the given problem, then the solution to the given Fredholm integral equation will be the sum of  $f(x)$  plus a linear combination of the Eigen functions and all these items can be addressed in terms of Fredholm theory. Where this Fredholm theory relates with the solution of a Fredholm integral equation with the resolvent kernel from the Fredholm integral equation and there we can discuss the same thing in terms of the three Fredholm theorems. So, in this lecture I can stop at here; the next two lectures will be on the three theorems of Fredholm and Halpern-Smith theory, those are related with the Fredholm integral equation, thank you for your attention.