

Course name: EMI /EMC and Signal Integrity: Principles, Techniques and Applications.

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Lecture 37: Development of crosstalk model infrequency domain

Welcome to 37th lecture of the course on EMIMC and Signal Integrity Principles, Techniques and Applications. In the previous class, we have started developing cross talk model. So, in this class, we will go further with that model. We have written up to these.

Crosstalk Model

$$\frac{d}{dz} [\tilde{V}(z)] = -[\tilde{Z}] [\tilde{I}_z] \quad \dots \quad (1)$$
$$\frac{d}{dz} [\tilde{I}(z)] = -[\tilde{Y}] [\tilde{V}_z] \quad \dots \quad (2)$$

So, if we differentiate it with respect to z and substitute the other that you know in transmission line, you have done that type of things. So, we get d 2. See now the equations are uncoupled. You see in the first equation only V_z is there, I_z is not there. In the second equation I_z is there, V_z is not there. Also note the order of multiplication for z and y . In the first one, z is the pre multiplier. In the second one, z is the post multiplier. They do not commute. So, please do not say that z and z into y is equal to y into z because the matrices are not diagonal. In general, in lossy transmission line, they do not commute. We will see later that for lossless case, they will commute. Now, either of these equation can be solved. If we either can find I_z along the whole line, current along the whole line or voltage along the whole line, we can determine from the other

what is the relation by that previous 1 and 2. So, let us solve the second equation. The general solution we know can be obtained in terms of I is equal to some transportation matrix T. So, this IM are the modal currents. Basically for waves, there will be a forward going wave, there is a backward going current into F. So, that we are calling modal currents and T is a transportation matrix. I and IM both are vectors of dimension 2 into 1. T is transportation matrix, its order is 2 into 2. So, if we substitute this solution, this is the solution we are assuming.

LECTURE 37: DEVELOPMENT OF CROSSTALK MODEL IN FREQUENCY DOMAIN

$$\frac{d^2}{dz^2} [\tilde{V}(z)] = [\tilde{Z}] [\tilde{Y}] [\tilde{V}(z)]$$

$$\frac{d^2}{dz^2} [\tilde{I}(z)] = [\tilde{Y}] [\tilde{Z}] [\tilde{I}(z)]$$

Solution $[\tilde{I}] = [\tilde{T}] [\tilde{I}_m]$

↑ 2x2
Transportation matrix

We substitute this solution in the second uncoupled equation that means in this equation number 2. So, what we get? We get sorry in this second uncoupled equation, I have shown it wrongly. This one, this equation we are putting that solution. So, we are getting $\frac{d^2}{dz^2} \tilde{I}_m z$ is equal to T^{-1} . The second equation y is the pre multiplier. So, if we can find a transportation matrix T so that y into z is equal to T^{-1} into z gets diagonalized, then the modal equation also becomes uncoupled. That means, what I am meaning is if $T^{-1} y$ becomes and this one is diagonal that means it will be $\gamma_g^2 \ 0 \ 0 \ \gamma_r^2$. If this is a diagonal matrix, so if we can find a T matrix such that $T^{-1} y$ into z into T is diagonal, then this \tilde{I}_m they gets uncoupled because in \tilde{I}_m there are $\tilde{I}_m g$ and $\tilde{I}_m r$. So, with this diagonalization $\tilde{I}_m g$ and $\tilde{I}_m r$ will be separated and we will be able to solve them. So, that time you see with this we can write this equation. So, if this then we get $\frac{d^2}{dz^2} \tilde{I}_m g z$ is equal to $\gamma_g^2 \ 0 \ 0$ and $\frac{d^2}{dz^2} \tilde{I}_m r z$ is equal to $\gamma_r^2 \ 0 \ 0$. So, this γ_g^2 it is now obvious that γ_g^2 and γ_r^2 are the eigenvalues of y into g matrix. So, γ_g^2 and γ_r^2 are eigenvalues, you know eigenvalues that you

have done in matrix. So, sorry and they are referred to propagation constants of the multi conductor transmission line. So, now once this is done we can write the solutions we know now they will be separately we can treat them.

$$\frac{d^2}{dz^2} [\tilde{I}_m(z)] = [\tilde{T}]^{-1} [\tilde{Y}] [\tilde{Z}] [\tilde{T}] [\tilde{I}_m(z)]$$

$$\text{iff} \rightarrow [\tilde{T}]^{-1} [\tilde{Y}] [\tilde{Z}] [\tilde{T}] = [\tilde{\gamma}^z] = \begin{bmatrix} \tilde{\gamma}_{G1}^z & 0 \\ 0 & \tilde{\gamma}_R^z \end{bmatrix}$$

$$\text{then} \rightarrow \frac{d^2 \tilde{I}_{mG}(z)}{dz^2} = \tilde{\gamma}_G^z \tilde{I}_{mG}(z)$$

$$\text{and} \frac{d^2 \tilde{I}_{mR}(z)}{dz^2} = \tilde{\gamma}_R^z \tilde{I}_{mR}(z)$$

So, we can write as $I_m(z)$ will be $e^{-\gamma z}$ to the power minus γz $I_m(z)$ plus $e^{+\gamma z}$ to the power γz $I_m(z)$ minus $I_m(z)$ is equal to. So, this is the solution now because of the uncoupled nature due to that T matrix. So, now several things are to be noted why I am saying uncoupled you see in $I_m(z)$ is assumed solution there is no $I_m(z)$ term. In $I_m(z)$ solution there is the $I_m(z)$ plus there is an $I_m(z)$ minus. Similarly in $I_m(z)$ there is only $I_m(z)$ plus and $I_m(z)$ minus. Now, also note the minus sign we know that current waves the forward wave and backward wave there is a minus between them to keep the direction of propagation same. In voltage waves both of them adds in current waves they oppose. And what are these $I_m(z)$ plus $I_m(z)$ minus $I_m(z)$ plus $I_m(z)$ minus are constants yet to be determined. So, you see how I got this type of form you see this equation this is a well known equation that from simple harmonic motion we know it into in complex notation $e^{-\gamma z}$ is a solution ok. The cos sign they change the form because if you twice differentiate cos there will be a minus sign come. Similarly if you twice differentiate sign there will be a minus sign come but for exponential terms $e^{-\gamma z}$ or $e^{+\gamma z}$ there is no minus sign comes that is why it is better and there is a relation by Euler's identity always it can be related to appropriate sinusoidal thing. So, that is why I have written

this that it will be sum of this. Now, let us write everything in a compact matrix form. So, in compact matrix form I can now again go back I have once shown it but we will write it like this that $\tilde{I}_m(z)$ is equal to $e^{-\tilde{\gamma}_A z}$ to the power minus $\tilde{I}_{m_A}^+$ plus $e^{\tilde{\gamma}_R z}$ to the power plus $\tilde{I}_{m_R}^-$. And where $e^{-\tilde{\gamma}_A z}$ is equal to or I can say plus minus in one way I can solve it $e^{-\tilde{\gamma}_A z}$ to the power minus $\tilde{I}_{m_A}^+$ plus $e^{\tilde{\gamma}_R z}$ to the power plus $\tilde{I}_{m_R}^-$. These are all for later references because we will manipulate these matrices that time this compactness will help us $\tilde{I}_m(z)$ $\tilde{I}_m(z)$ plus minus this also then we write this $\tilde{I}_m(z)$ plus minus.

$$\tilde{I}_{m_A}(z) = e^{-\tilde{\gamma}_A z} \tilde{I}_{m_A}^+ - e^{\tilde{\gamma}_R z} \tilde{I}_{m_R}^-$$

$$\tilde{I}_{m_R}(z) = e^{-\tilde{\gamma}_R z} \tilde{I}_{m_R}^+ - e^{\tilde{\gamma}_A z} \tilde{I}_{m_A}^-$$

$\tilde{I}_{m_A}^+, \tilde{I}_{m_A}^-, \tilde{I}_{m_R}^+, \tilde{I}_{m_R}^- \rightarrow \text{constants yet to be determined}$

$$[\tilde{I}_m(z)] = [e^{-\tilde{\gamma} z}] [\tilde{I}_m^+] - [e^{\tilde{\gamma} z}] [\tilde{I}_m^-]$$

where $[e^{\pm \tilde{\gamma} z}] = \begin{bmatrix} e^{\pm \tilde{\gamma}_A z} & 0 \\ 0 & e^{\pm \tilde{\gamma}_R z} \end{bmatrix}$

$$[\tilde{I}_m^\pm] = \begin{bmatrix} \tilde{I}_{m_A}^\pm \\ \tilde{I}_{m_R}^\pm \end{bmatrix}$$

So, now actual currents we have seen the solution we have taken as this that $I(z)$ is equal to t matrix into IM matrix. So, now we will put the assumed solution. So, $e^{-\tilde{\gamma}_A z}$ to the power minus \tilde{I}_m^+ plus $e^{\tilde{\gamma}_R z}$ to the power plus \tilde{I}_m^- . So, let me call this equation number 3. Now, from equation 2 we have to write this equation 2. Can we say that what was equation 2 let us see, this was equation 2. So, what is $V(z)$? It is $-\tilde{Y}^{-1} d/dz$ of $I(z)$. So, from equation 2 I can write $V(z)$ is equal to $-\tilde{Y}^{-1} d/dz$ of $I(z)$. So, $I(z)$ I know. So, it will be t minus $\tilde{\gamma}$ $e^{-\tilde{\gamma}_A z}$ to the power minus \tilde{I}_m^+ plus $\tilde{\gamma}$ $e^{\tilde{\gamma}_R z}$ to the power plus \tilde{I}_m^- . So, this is equation number 4. Already we have seen this relation that t inverse \tilde{Y}^{-1} is equal to $\tilde{\gamma}^{-2}$. So, we have $\tilde{Y}^{-1} t$ into $\tilde{\gamma}$. You see this minus $\tilde{\gamma}$, this minus sign and this minus sign will go. So, now, already we have seen that I am again writing already seen t inverse \tilde{Y}^{-1} all phasors that is why tilde over each matrix is equal to $\tilde{\gamma}^{-2}$. So, we can write that we can write z t . So, $\tilde{\gamma}^{-2}$ inverse is equal to $\tilde{Y}^{-1} t$ $\tilde{\gamma}$. So, instead of this $\tilde{Y}^{-1} t$ $\tilde{\gamma}$ this minus will go. I will write z t $\tilde{\gamma}^{-2}$ inverse here.

So, this equation will come here that $V z$ is equal to $z t \gamma$ inverse. So, this is the equation number 5. Now, here I will do a trick that is because I know so I am doing I can always do this then I will go on writing that second bracket thing $e^{-\gamma z}$ to the power minus γz I_m^+ plus $e^{\gamma z}$ to the power γz I_m^- . So, let me call this equation, equation number 4. So, equation number 3 was expression of $I(z)$ equation 4 is expression of $V(z)$. Now, you see what was $I(z)$? $I(z)$ is t into second bracket that bracket has not been closed there. Here also I have t into the second bracket that means, this term if it is $I(z)$. So, what is this term $V(z)$ is equal to something into current voltage is equal to something into current. So, can I say that this one is something like impedance. So, this is actually the characteristic impedance of the line.

The image shows a whiteboard with handwritten mathematical derivations. At the top, the current $I(z)$ is expressed in terms of forward and backward waves. Below this, the voltage $V(z)$ is derived from the current equation using the ABCD parameters of the transmission line. The derivation involves matrix operations and simplification, leading to an expression for $V(z)$ that includes the characteristic impedance Z_0 .

$$[I(z)] = [T] [I_m]$$

$$= [T] \left\{ [e^{-\gamma z}] [I_m^+] - [e^{+\gamma z}] [I_m^-] \right\} \dots (3)$$

From Eqn. (2)

$$[V(z)] = -[Y]^{-1} [T] [-\gamma] \left\{ [e^{-\gamma z}] [I_m^+] + [e^{+\gamma z}] [I_m^-] \right\}$$

Already seen

$$[T]^{-1} [Y] [Z] [T] = [\gamma z]$$

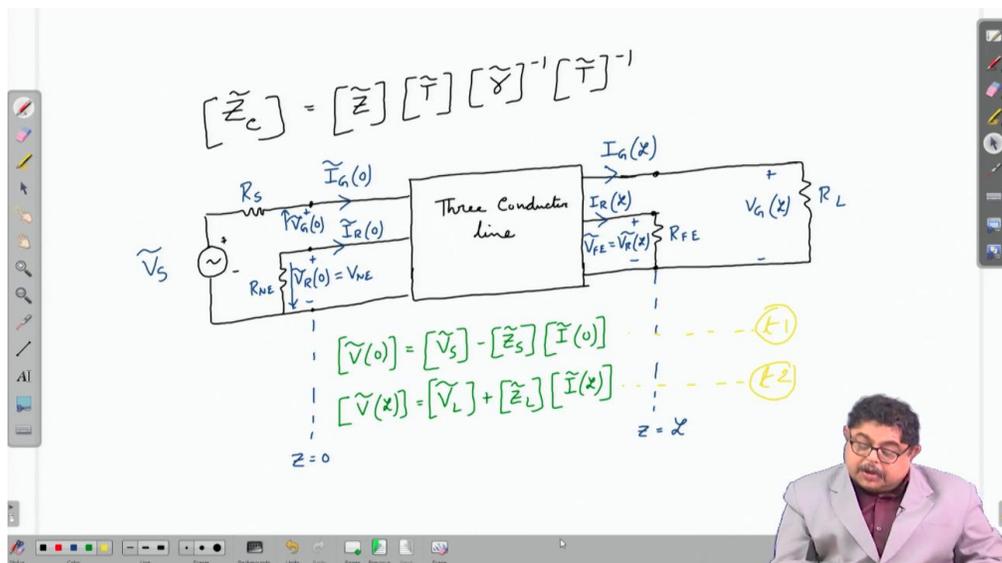
so,

$$[Z] [T] [Y]^{-1} = [Y]^{-1} [T] [\gamma]$$

$$[V(z)] = [Z] [T] [Y]^{-1} [T]^{-1} [T] \left\{ [e^{-\gamma z}] [I_m^+] + [e^{+\gamma z}] [I_m^-] \right\} \dots (4)$$

So, this says that I can define a characteristic impedance as $z t \gamma$ inverse. So, that means, we can write $V(z)$ is equal to $z c$ into $I(z)$. So, in a compact notation I know this, but I have not done one thing that we have not determined the 4 unknown constants I_m^+ plus I_m^- plus I_m^+ plus I_m^- that we have not done. So, that we will do now, how to do it? We will find the terminal conditions. So, it is a 3 conductor line. So, we will have 2 input ports, we have 2 output ports, one port is between generator and reference, another port is between receptor and reference. So, in input side 2 ports,

output side 2 ports. So, we will find 4 terminal conditions from which 4 unknown constants we will define. So, for that So, this is the source side, the source side I have a voltage source and the source impedance z_s is there, I will in actual writing I will take it as d_s , but while showing I am calling it r_s , then the current that is entering through port of the generator is I_g , it is at z is equal to 0. So, I am writing $I_g(0)$, R_{ne} is the lumped circuitry that is in the near side of the source for receptor, I am calling that full circuitry as R_{ne} , you can again call it Z_{ne} etcetera, but for simplicity we are calling it R_{ne} . So, voltage developed between the receptor port is $V_r(0)$ that is V_{ne} . Similarly, the current that is coming to the coming out of the generator port, I am calling it $I_g(0)$, the current that is carried there should be a port that is $I_r(0)$, then this one I am calling R_{fe} , the this is this voltage plus minus assumed V_{fe} , this is basically $V_r(0)$. And this voltage is $V_g(0)$ plus minus, this is R_L again load, R_{fe} is the lumped effect of all the circuitry associated, there is another voltage to be shown here at $V_g(0)$ plus and minus, so it is from here to here. And I can write some terminal conditions that V_{naught} is equal to V_s minus, you say I am writing Z_s , but actually I have shown R_s that I explained. So, so $V(0)$ is the matrix, so $V_g(0)$ and $V_r(0)$ are two elements of this, this is a vector is equal to V_s minus Z_s into I_{naught} and V_l , again V_l comprises of $V_g(0)$ and $V_r(0)$ is equal to V_l is the port voltage plus Z_l into I_l . So, these equations are my terminal equation, I am calling this T1, I am calling this T2,



where what is V_s , V_s from the circuit we can see, V_s is the source voltage for receptor, there is no source voltage, what is V_l , you see for V_l there are V_l , there are no voltages, all the voltages are in this lump part. Then what is Z_s , Z_s is in our case R_s 0 0 R_{ne} near end and Z_l will be R_l 0 R_{fe} . So, I have written terminal conditions and this is the terminal circuit model. So, from this we will have to find the four unknown

constants, once we find that with this terminal conditions we will be able to evaluate V_f and V_n that is our data from the start I have said that, that from all other knowledge I will have to finally find V_f and V_n . Today time is up, in the next class we will start developing that. Thank you.

where,

$$\begin{bmatrix} \tilde{V}_S \\ \tilde{V}_L \end{bmatrix} = \begin{bmatrix} \tilde{V}_S \\ 0 \end{bmatrix}$$
$$\begin{bmatrix} \tilde{V}_L \\ \tilde{V}_L \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$
$$\begin{bmatrix} \tilde{Z}_S \\ \tilde{Z}_S \end{bmatrix} = \begin{bmatrix} R_S & 0 \\ 0 & R_{NE} \end{bmatrix}$$
$$\begin{bmatrix} \tilde{Z}_L \\ \tilde{Z}_L \end{bmatrix} = \begin{bmatrix} R_L & 0 \\ 0 & R_{FE} \end{bmatrix}$$

The image shows a digital whiteboard interface with a toolbar on the left and right sides. The toolbar includes icons for drawing tools like a pen, eraser, and highlighter, as well as navigation tools like a mouse cursor and a search icon. At the bottom of the whiteboard, there is a Windows taskbar with various application icons. In the bottom right corner of the whiteboard, there is a small video feed of a man with glasses and a mustache, wearing a light-colored jacket over a dark shirt.